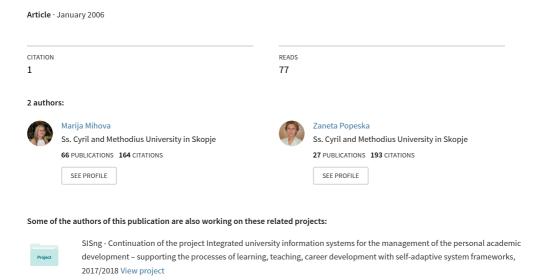
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# Minimal path and cut vectors of binary type multi-state monotone systems



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## MINIMAL PATH AND CUT VECTORS OF BINARY TYPE MULTI-STATE MONOTONE SYSTEMS

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**Abstract**. Binary type multi-state systems are systems that can be regarded as a binary systems at any level. We give a characterization by the structure of their minimal path and minimal cut vectors. Also we present some relations between minimal path and minimal cut vectors of different levels of such systems.

#### 1. Introduction

Consider a multi state system with n components, such that, all components and whole system can be found in M+1 levels, from the set  $S=\{0,1,\ldots,M\}$ . The level M is the level of perfect work of the component or the system and the level 0 is the level of their total failure. We assume that for i>j, the system or the component works with higher quality in state i then in state j. Let  $x_i$  be the state of the i-th component of the system, for  $x_i \in S$  and  $1 \le i \le n$  and  $\mathbf{x} = (x_1, x_2, \ldots, x_n)$  the state vector. Then  $E = \underbrace{S \times, \ldots, \times S}$  is the state set of

the system. For a given system we can define a structure function  $\phi(\mathbf{x}): E \to S$  which represents the level of the system when it is in state  $\mathbf{x}$ . The state vector  $\mathbf{x}$  is **path vector** of level j iff  $\phi(\mathbf{x}) \geq j$ , and it is **cut vector** of level j iff  $\phi(\mathbf{x}) < j$ .

We use the definition for minimal path and cut vectors given in [1].

**Definition 1.** The vector  $\mathbf{x}$  is minimal path vector of level j if  $\phi(\mathbf{x}) \geq j$  and  $\phi(\mathbf{y}) < j$  for all  $\mathbf{y} < \mathbf{x}$ ;

The vector  $\mathbf{x}$  is minimal cut vector of level j if  $\phi(\mathbf{x}) < j$  and  $\phi(\mathbf{y}) \geq j$  for all  $\mathbf{y} > \mathbf{x}$ .

For each state vector  $\mathbf{x} \in E$  and  $\forall j \in S$  we define the vector  $\mathbf{x}^j$  by:

$$\mathbf{x}^{j} = (x_{1}^{j}, x_{2}^{j}, \dots, x_{n}^{j}), \quad x_{i}^{j} = \begin{cases} 1, & x_{i} \ge j \\ 0, & x_{i} < j \end{cases}.$$

Similarly let

$$\phi^{j}(\mathbf{x}) = \begin{cases} 1, & \phi(\mathbf{x}) \ge j \\ 0, & \phi(\mathbf{x}) < j \end{cases}.$$

According [1], a system is a monotone multi state system MMS if its structure function satisfies:

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- 1)  $\phi(\mathbf{x})$  is non-decreasing in each argument
- 2)  $\phi(\mathbf{0}) = 0$ ,  $\phi(\mathbf{M}) = M$ , where  $\mathbf{0} = (0, 0, \dots, 0)$ , and  $\mathbf{M} = (M, M, \dots, M)$ .

**Definition 2.** A system is a binary type monotone multi-state system (BTMMS) if  $\forall j \in \{0, 1, ..., M\}$  there exists binary structure function  $\phi_j$  such that

$$\phi(\mathbf{x}) \ge j \Leftrightarrow \phi_j(\mathbf{x}^j) = 1. \tag{1}$$

2. STRUCTURE OF MINIMAL PATH AND CUT VECTORS OF BINARY TYPE MMS

**Theorem 1.** A n-component monotone multi-state system with structure function  $\phi: E \to S$  is a BTMMS if and only if for any  $j = \overline{1, M}$ , minimal path vectors of level j are of the following form:

$$\mathbf{x} = (x_1, x_2, \dots, x_{n-1}, x_n), \ \forall i = \overline{1, n}, \ x_i \in \{0, j\}.$$
 (2)

*Proof.* First we will proof that the minimal path vectors of BTMMS are of the form (2).

Suppose that we have BTMMS with structure function  $\phi$ . From Definition 2 there exists a binary type function  $\phi_j$  that satisfies (1). Let  $\mathbf{x}$  be a minimal path vector of level j of the system.

1) Suppose that there exists  $k \in S$ , such that  $x_k = i$ , for 0 < i < j. Let

$$\mathbf{y} = (x_1, \dots, x_{k-1}, 0, x_{k+1}, \dots, x_n).$$

Then,  $\mathbf{y} < \mathbf{x}$  and  $\mathbf{y}^j = \mathbf{x}^j$ . From  $\mathbf{y}^j = \mathbf{x}^j$ , we have that  $\phi_j(\mathbf{y}^j) = \phi_j(\mathbf{x}^j) = 1$ , and since the system is BTMMS,  $\phi(\mathbf{y}) \ge j$ . Consequently  $\mathbf{y}$  is a smaller path vector of level j then  $\mathbf{x}$ , which is in contradiction with the assumption that  $\mathbf{x}$  is minimal path vector of level j. So, we have that the vector  $\mathbf{x}$  has no coordinates between 0 and j.

2) Suppose that there exists  $k \in S$ , such that  $x_k = i$ , where j < i < M. Let

$$y = (x_1, \ldots, x_{k-1}, j, x_{k+1}, \ldots, x_n).$$

We have that  $\mathbf{y} < \mathbf{x}$ . Also,  $\mathbf{y}^j = \mathbf{x}^j$ , so  $\phi_j(\mathbf{y}^j) = \phi_j(\mathbf{x}^j) = 1$ . From the definition of BTMMS,  $\phi(\mathbf{y}) \geq j$ . Again we obtain that  $\mathbf{y}$  is a smaller path vector of level j than  $\mathbf{x}$ , which is in contradiction with the assumption that  $\mathbf{x}$  is minimal path vector of level j. Therefore the vector  $\mathbf{x}$  has no coordinates between j and M.

From 1) and 2) we have that the coordinates of x are either 0 or j.

To proof the converse, i.e. that if the minimal path vectors of a MMS are of the form (2), then the system is of binary type, we define binary function  $\phi_j$ :  $\{0,1\}^n \to \{0,1\}$  by:

$$\phi_j(\mathbf{x}^j) = \phi^j(\mathbf{x}). \tag{3}$$

The proof will be complete if we proof that this function is well defined and that  $\phi(\mathbf{x}) \geq j \Leftrightarrow \phi_j(\mathbf{x}^j) = 1$ .

Let  $\mathbf{x}^j = \mathbf{y}^j$  such that  $\phi_j(\mathbf{x}) \neq \phi_j(\mathbf{y})$ . From (3) we have that  $\phi^j(\mathbf{x}) \neq \phi^j(\mathbf{y})$ . Without lose of generality we can assume  $\phi^j(\mathbf{x}) = 1$  and  $\phi^j(\mathbf{y}) = 0$ . Let

$$\mathbf{z} = \left\{ \begin{array}{ll} j, & \mathbf{x}_k \geq j \\ 0, & \mathbf{x} < j \end{array} \right. = \left\{ \begin{array}{ll} j, & \mathbf{y}_k \geq j \\ 0, & \mathbf{y} < j \end{array} \right..$$

Since  $\phi(\mathbf{x}) \geq j$ , there is a minimal path vector  $\mathbf{v}$  of level j, of the form (2), such that  $\mathbf{v} \leq \mathbf{x}$ . Then  $\mathbf{v} \leq \mathbf{z}$ . This implies  $\phi(\mathbf{z}) \geq \phi(\mathbf{v}) \geq j$ , i.e.  $\mathbf{z}$  is path vector of level j.

On the other hand,  $\mathbf{z} \leq \mathbf{y} \Rightarrow \phi(\mathbf{z}) \leq \phi(\mathbf{y}) < j$  which is a contradiction. So, the function  $\phi_j$  is well defined.

At the and we will proof that (1) holds.

$$\phi(\mathbf{x}) \ge j \Leftrightarrow \phi^j(\mathbf{x}) = 1 \Leftrightarrow \phi_j(\mathbf{x}^j) = 1.$$

**Theorem 2.** A n-component MMS with structure function  $\phi: E \to S$  is a BT-MMS if and only if for every  $j = \overline{1, M}$ , the minimal cut vectors of level j are of the following form:

$$\mathbf{x} = (x_1, x_2, \dots, x_{n-1}, x_n), \ \forall i = \overline{1, n}, \ x_i \in \{M, j-1\}.$$
 (4)

*Proof.* First, we will proof that the minimal cut vectors of BTMMS are of the form (4).

Suppose that we have BTMMS with structure function  $\phi$ . From Definition 2 there exists a binary type function  $\phi_j$  that satisfies (1). Let  $\mathbf{x}$  be a minimal cut vector of level j.

1) Suppose that there is  $k \in S$  such that  $x_k = i$ , for i < j - 1. Let

$$\mathbf{y} = (x_1, \dots, x_{k-1}, j-1, x_{k+1}, \dots, x_n).$$

It is clear that y > x and  $y^j = x^j$ . Since  $y^j = x^j$ 

$$\phi_j(\mathbf{y}^j) = \phi_j(\mathbf{x}^j) = 0 \Rightarrow \phi(\mathbf{y}) < j \Rightarrow \phi^j(\mathbf{y}) = 0.$$

Therefore,  $\mathbf{y}$  is a cut vector of level j, bigger then  $\mathbf{x}$ , which is in contradiction with the assumption that  $\mathbf{x}$  is a minimal cut vector. So, the vector  $\mathbf{x}$  has no coordinates smaller then j-1.

2) Now, suppose that there is  $k \in S$ , such that  $j-1 < x_k < M$ . Let

$$y = (x_1, \ldots, x_{k-1}, M, x_{k+1}, \ldots, x_n) > x.$$

Then,  $\mathbf{y}^j = \mathbf{x}^j$ , so

$$\phi_j(\mathbf{y}^j) = \phi_j(\mathbf{x}^j) = 0 \Rightarrow \phi(\mathbf{y}) < j \Rightarrow \phi^j(\mathbf{y}) = 0.$$

We get that  $\mathbf{y}$  is a cut vector of level j, bigger then  $\mathbf{x}$ , which is not possible since  $\mathbf{x}$  is a minimal cut vector. So the vector  $\mathbf{x}$  has no coordinates  $x_k$ , such that  $j-1 < x_k < M$ .

From 1) and 2) we have that all coordinates of x are either M or j-1.

Now suppose that if the minimal cut vectors of MMS are of the form (4). Define a function  $\phi_i$  by:

$$\phi_j(\mathbf{x}^j) = \phi^j(\mathbf{x}). \tag{5}$$

First we will proof that this function is well defined. Let  $\mathbf{x}$  and  $\mathbf{y}$  be two vectors such that  $\mathbf{x}^j = \mathbf{y}^j$  and  $\phi_j(\mathbf{x}) \neq \phi_j(\mathbf{y}) \Leftrightarrow \phi^j(\mathbf{x}) \neq \phi^j(\mathbf{y})$ . We can assume that  $\phi^j(\mathbf{x}) = 1$  and  $\phi^j(\mathbf{y}) = 0$ . Let  $\mathbf{z} = (z_1, \dots, z_n)$  sach that:

$$z_k = \left\{ \begin{array}{ll} j-1, & x_k < j \\ M, & x_k \ge j \end{array} \right. = \left\{ \begin{array}{ll} j-1, & y_k < j \\ M, & y_k \ge j \end{array} \right.$$

Since  $\phi(\mathbf{y}) \leq j$ , we have that there exists a minimal cut vector  $\mathbf{v}$  for level j that satisfies (4), such that  $\mathbf{v} \geq \mathbf{y}$ . This vector also satisfies  $\mathbf{v} > \mathbf{z}$ . Consequently,  $j > \phi(\mathbf{v}) \geq \phi(\mathbf{z})$ .

On the other hand,  $\mathbf{z} \geq \mathbf{x} \Rightarrow \phi(\mathbf{z}) \geq \phi(\mathbf{x}) \geq j$ . We obtain that  $j > \phi(\mathbf{x}) \geq j$ , which is not possible, so the function is well defined.

To complete the proof we will show that (1) is true.

$$\phi(\mathbf{x}) \ge j \Leftrightarrow \phi^j(\mathbf{x}) = 1 \Leftrightarrow \phi_j(\mathbf{x}^j) = 1,$$

so the system is a BTMMS.

### 3. Relations between minimal path and cut vectors of different levels

From Theorem 2 and Theorem 1 in the case of BTMMS we can talk about minimal path set and minimal cut set.

**Definition 3.** The set  $A \subseteq S$  is a minimal path set of level j if and only if there is a minimal path vector of level j such that  $\forall i \in A$ ,  $x_i = j$ , and  $\forall i \in A^c$ ,  $x_i = 0$ . The set  $A \subseteq S$  is a minimal cut set of level j if and only if there is a minimal

**Proposition 1.** For a given BTMMS with structure function  $\phi$  and a minimal path set A of level j, for all k > j, there is no minimal path set B of level k, such

cut vector of level j such that  $\forall i \in A, x_i = j-1, \text{ and } \forall i \in A^c, x_i = M.$ 

that  $B \subset A$ .

Proof. Suppose the opposite, i.e. that in this BTMMS, there is a minimal path set A of level j and a minimal path set B of level k, for j < k, so that  $B \subset A$ . We define vectors  $\mathbf{x} = (x_1, \dots, x_n)$ ,  $\mathbf{y} = (y_1, \dots, y_n)$  and  $\mathbf{z} = (z_1, \dots, z_n)$  as:

$$x_i = \left\{ \begin{array}{ll} j, & i \in A \\ 0, & i \in A^c \end{array} \right., \quad y_i = \left\{ \begin{array}{ll} k, & i \in B \\ 0, & i \in B^c \end{array} \right., \quad z_i = \left\{ \begin{array}{ll} j, & i \in B \\ 0, & i \in B^c \end{array} \right..$$

It is clear that  $\mathbf{x}$  is a minimal path vector of level j. Also  $\mathbf{y}$  is a minimal path vector of level k > j, so  $\phi(\mathbf{y}) > j$ . Since  $\mathbf{z} < \mathbf{x}$  we have that  $\phi(\mathbf{z}) < j$ . On the other hand  $\mathbf{z}^j = \mathbf{y}^j$ , so  $\phi_j(\mathbf{z}^j) = \phi_j(\mathbf{y}^j)$ , which is no true. These means that our assumption is not true, i.e. there is no minimal path set B of level k > j, such that  $B \subset A$ .

**Proposition 2.** For a given BTMMS with structure function  $\phi$  and a minimal path set B of level k, for all j < k, there is a minimal path set A of level j, such that  $A \subset B$ .

*Proof.* Let B be the minimal path set of level k, and j < k. We define vectors  $\mathbf{x} = (x_1, \dots, x_n), \mathbf{y} = (y_1, \dots, y_n)$  as:

$$x_i = \left\{ \begin{array}{ll} j, & i \in B \\ 0, & i \in B^c \end{array} \right., \quad y_i = \left\{ \begin{array}{ll} k, & i \in B \\ 0, & i \in B^c \end{array} \right..$$

It is clear that  $\mathbf{y}$  is a minimal path vector of level k, so  $\phi(\mathbf{y}) = k > j$ . Also we have that  $\mathbf{x}^j = \mathbf{y}^j$ , so  $\phi_j(\mathbf{x}^j) = \phi_j(\mathbf{y}^j)$ . There of  $\phi(\mathbf{x}) \geq j$ , so  $\mathbf{x}$  is a path vector of level j. Sequentially, there is a minimal path vector  $\mathbf{z}$  of level j smaller or equal to  $\mathbf{x}$ . From Theorem 1, the coordinates of  $\mathbf{z}$  are either 0 or j, so there is a set  $A \subseteq B$  such that  $x_i = \begin{cases} j, & i \in A \\ 0, & i \in A^c \end{cases}$ . This set A is a minimal path set of level j.

**Proposition 3.** For a given BTMMS with structure function  $\phi$  and a minimal cut set A of level j, for all k < j, there is no minimal cut set B of level k, such that  $B \subset A$ .

*Proof.* Suppose the opposite, i.e. that in this BTMMS, there is a minimal cut set A of level j and minimal cut set B of level k, for j > k, such that  $B \subset A$ . We define vectors  $\mathbf{x} = (x_1, \dots, x_n)$ ,  $\mathbf{y} = (y_1, \dots, y_n)$  and  $\mathbf{z} = (z_1, \dots, z_n)$  as:

$$x_i = \left\{ \begin{array}{ll} j-1, & i \in A \\ M, & i \in A^c \end{array} \right., \quad y_i = \left\{ \begin{array}{ll} k-1, & i \in B \\ M, & i \in B^c \end{array} \right., \quad z_i = \left\{ \begin{array}{ll} j-1, & i \in B \\ M, & i \in B^c \end{array} \right.$$

It is clear that  $\mathbf{x}$  is a minimal cut vector of level j and  $\mathbf{y}$  is a minimal cut vector of level k. Since  $\mathbf{y}$  is a cut vector of level k,  $\phi(\mathbf{y}) < k < j$ . There of  $\phi_j(\mathbf{y}) = 0$ . On the other side,  $\mathbf{z}^j = \mathbf{y}^j$ , so  $\phi_j(\mathbf{z}^j) = \phi_j(\mathbf{y}^j) = 0 \Rightarrow \phi(\mathbf{z}) < j$ . This means that  $\mathbf{z}$  is bigger cut vector of level j then the vector  $\mathbf{x}$ , which is in contradiction with our assumption that  $\mathbf{x}$  is a minimal cut vector of level j.

**Proposition 4.** For a given BTMMS with structure function  $\phi$  and a minimal cut set B of level k, for all j > k, there is a minimal cut set A of level j, such that  $A \subseteq B$ .

*Proof.* Let B be the minimal cut set of level k, and j > k. We define vectors  $\mathbf{x} = (x_1, \dots, x_n), \mathbf{y} = (y_1, \dots, y_n)$  as:

$$x_i = \left\{ \begin{array}{ll} j-1, & i \in B \\ M, & i \in B^c \end{array} \right., \quad y_i = \left\{ \begin{array}{ll} k-1, & i \in B \\ M, & i \in B^c \end{array} \right.$$

It is clear that  $\mathbf{y}$  is a minimal cut vector of level k, so  $\phi(\mathbf{y}) < k < j$ . Also we have that  $\mathbf{x}^j = \mathbf{y}^j$ , so  $\phi_j(\mathbf{x}^j) = \phi_j(\mathbf{y}^j)$ . There of we have that  $\phi(\mathbf{x}) < j$ , so  $\mathbf{x}$  is a cut vector of level j. Sequentially, there is a minimal cut vector  $\mathbf{z}$  of level j bigger or equal then  $\mathbf{x}$ . From Theorem 2, the coordinates of  $\mathbf{z}$  are either M or j-1, so there is a set  $A \subseteq B$  such that  $x_i = \left\{ \begin{array}{ll} j-1, & i \in A \\ M, & i \in S \setminus A \end{array} \right.$  This set A is a minimal cut set of level j.

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