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# **Technological Solutions for Sign Language Recognition: A Scoping Review of Research Trends, Challenges, and Opportunities**

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ABSTRACT Sign languages are critical in conveying meaning by the use of a visual-manual modality and are the primary means of communication of the deaf and hard of hearing with their family members and with the society. With the advances in computer graphics, computer vision, neural networks, and the introduction of new powerful hardware, the research into sign languages has shown a new potential. Novel technologies can help people learn, communicate, interpret, translate, visualize, document, and develop various sign languages and their related skills. This paper reviews the technological advancements applied in sign language recognition, visualization, and synthesis. We defined multiple research questions to identify the underlying technological drivers that strive to improve the challenges in this domain. This study is designed in accordance with the PRISMA methodology. We searched for articles published between 2010 and 2021 in multiple digital libraries (i.e., Elsevier, Springer, IEEE, PubMed, and MDPI). To automate the initial steps of PRISMA for identifying potentially relevant articles, duplicate removal and basic screening, we utilized a Natural Language Processing toolkit. Then, we performed a synthesis of the existing body of knowledge and identified the different studies that achieved significant advancements in sign language recognition, visualization, and synthesis. The identified trends based on analysis of almost 2000 papers clearly show that technology developments, especially in image processing and deep learning, are driving new applications and tools that improve the various performance metrics in these sign language-related task. Finally, we identified which techniques and devices contribute to such results and what are the common threads and gaps that would open new research directions in the field.

**INDEX TERMS** Sign language recognition, systematic review, sign language visualization.

#### I. INTRODUCTION

People are considered to have a hearing loss when they are not able to hear under a hearing threshold of 25dB or less in

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both ears. Around 430 million people worldwide have disabling hearing loss, and it is estimated that by 2050 over 700 million people will have disabling hearing loss.<sup>1</sup> Hearing

<sup>&</sup>lt;sup>1</sup>World Health Organisation (2022, March 22), Deafness and hearing loss. Retrieved from https://www.who.int/news-room/fact-sheets/detail/deafnessand-hearing-loss

loss can be mild, moderate, severe, or profound. "Hard of hearing" individuals have a hearing loss ranging from mild to severe, while "Deaf" individuals mostly have profound hearing loss.

Hearing loss is one of the most common chronic impairments that appear with age as degeneration of sensory cells. It results from different congenital or acquired causes (e.g., genetic causes, complications at birth, infectious diseases, exposure to excessive noise, among others). It is known as "Presbycusis" and affects approximately one-third of people over 65 years of age, and it cannot be reversed [1]. However, it can be effectively treated with common hearing aids and communication devices. Moreover, some disruptive assistive technologies based on Artificial Intelligence are emerging to improve the well-being and quality of life of hard of hearing and deaf individuals.

The problems tackled by assistive technologies are numerous and spread around different fields. Newly developed technologies and Information Technology (IT) driven and supported systems are at the forefront of the assistive technologies field. One of the many fields of application of assistive technologies is improving the life quality of hard of hearing and deaf persons.

Hard-of-hearing persons usually communicate through spoken language and can benefit from hearing aids, cochlear implants, and other assistive devices, as well as captioning. On the other hand, deaf persons face challenges in everyday communication that can significantly impact daily life, causing feelings of loneliness, isolation, and frustration, particularly among older people with hearing loss. One of the challenges for this community is proper integration in everyday "normal" society.

Sign languages are classified as natural languages and exhibit all the design features of other natural languages [2], [3]. Sign languages' visual and spatial nature and their variability present an exciting challenge for research in several scientific fields, such as linguistics, medicine, machine learning, computer vision, natural language processing, and computer graphics.

Interpretation and linguistics of sign languages are primarily concerned with the meaning conveyed using the sign language. With the recognition of sign languages as natural languages in the late 1970 and early 1980, linguist research took an in-depth look into this field [4]. Neural aspects are considered for fully grasping the connection between sign and phonetic languages. Natural language processing is also concerned with interpretation, a task similar to the interpretation and comprehension problems.

Sign language synthesis and visualization is an area that tackles visualization issues of sign languages and the creation of signed speech. This field researches and develops means of realistically "spoken" sign languages, using video and image sequences or digital characters [5].

Sign Language Recognition (SLR) is the scientific area responsible for capturing and translating sign speech using computer vision and artificial intelligence techniques [6].

In this paper, we focus on sign language research, a relatively young field that took off with the breaking research of William Stokoe [9], [10]. When tackling sign languages, we have identified three areas prominent for research: interpretation and linguistics of sign languages, sign language synthesis and visualization, and sign language recognition (SLR). Considering the importance of sign languages for the communication of millions of people across the world and the rapid technological developments, this article performs a scoping review of the most recent technologies applied in sign language recognition. One of the novelties of our work is that we start from a systematic mapping (i.e., a scoping review) where the trends in literature in the last decade are explored so that emerging technologies, sensors, algorithms can be analyzed. Then, we proceed in a more detail-oriented fashion that is more common of systematic reviews where we identify the most significant works in the field. To that end, we use an NLP-based tool to support and simplify the literature review, which, as a methodological approach, is novel and considerably reduces the manual effort usually involved in such activities.

The remainder of the paper is structured as follows. Section II discusses the related systematic reviews, and section III discusses our methodology for this paper. Section IV presents the results of our work, and section V discusses them. Finally, section VI concludes the paper.

#### **II. RELATED WORK**

This section covers other literature reviews relevant to the domain of this study. First we analyze most important recent works for sign language recognition. Then, we analyze recent systematic surveys in gesture recognition. Each area of research into sign languages has a vast amount of valuable research that needs to be filtered and analyzed. Surprisingly, few literature reviews have considered gesture and sign language analysis.

## A. LITERATURE REVIEWS IN SIGN LANGUAGE RECOGNITION

In 2011, Cooper *et al.* [6] provided an excellent review on sign language recognition approaches and challenges. The publication focuses on all aspects of sign language recognition (SLR): sign language linguistics, data acquisition related to sign languages, and approaches for sign language recognition. The linguistics portion describes some complexity in sign languages, like body posture and non-manual features. The data acquisition section enumerates the approaches for acquiring sign languages available at that time (data gloves, images and video input, depth-based cameras). It also listed the prominent sign language datasets that have been obtained using the methods. Also, the review discusses the main approaches of hand pose acquisition, as well as individual fingerspelling and other non-manual features. As for

recognition, the authors describe the state-of-the-art approaches, focusing on individual or continuous sign recognition. Various approaches using various types of Neural Networks, Hidden Markov Models and their variations (like Parallel HMM), decision trees, and self-organizing maps are utilized for various parts of SLR.

Similarly, in 2013, Toiba and Elons [11] discuss the developments in sign language recognition, taking into consideration much of the results mentioned by Cooper *et al.* and focusing on neural network approaches for SLR. They report recent results (as of the time) near 90% recognition for specific and carefully chosen cases. The paper, however, does not present a methodology of the surveyed results and provides a more general overview of the field.

Authors of [12] created a taxonomy to describe the latest research divided into four main categories: development, framework, other hand gesture recognition, and reviews, and surveys. Also, the authors created a roadmap and discussed the limitation of the use of this technology.

Er-Rady *et al.* [13] in 2017 published a survey about automatic sign language recognition. In it, they describe the approaches as well as the best methodologies for sign language recognition. In the paper, the authors explain the complexity of data acquisition as well as the features of the manual features of sign languages as well as other properties that the modality allows (*e.g.* facial expressions). They also describe the most common components that should be present in a system that uses an Automatic Speech Recognition system (ASLR).

A comprehensive review of recent works for sign language recognition is presented in [14], where authors defined a taxonomy to group existing works and discuss their pros and cons. The article also discusses features, modalities, evaluation metrics, applications, and datasets. Even though our work is on a similar topic, we focus on technological solutions, particularly those applying advances in camera technologies and machine learning methods. Likewise, we also analyze the publications in the recent decade at various publishers and identify the emerging trends and promising directions for future work.

A quantitative survey of state of the art in sign language recognition is presented in [15], where authors centered the research for the creation of a framework of the hand recognition system composed by image datasets, preprocessing, feature extraction, image segmentation, and classification with supervised and unsupervised learning strategies. The authors' motivation was to increase the susceptibility, decrease computational complexity, increase classification rate, and reduce the error rate. Similarly, our review is focused on the different methods for the recognition of sign language, but we included more recent studies.

Authors of [16] present a review of hand gesture and sign language recognition techniques. Unlike it, our survey presents more quantitative metrics about the trends and also shows the most relevant works, including novel techniques that have emerged in the recent years not covered by this paper.

In [17] a critical review and analysis of machine learning methods for sign language recognition is presented. It provides a comprehensive review of artificial intelligent methods applied in sign language recognition systems and brief overview of the feature extraction and segmentation methods. Unlike it, our work covers the wider field of visualization and interpretation of sign languages.

In [18], the authors presented the analysis of existing methods related to sign language capturing, recognition, translation, and representation, also showing their pros and cons. In addition, the authors analyzed the applicability of the studies. However, this study is only focused on artificial intelligence techniques and their applicability for sign language recognition.

#### **B. LITERATURE REVIEWS IN GESTURE RECOGNITION**

A field that is in close connection to Sign language recognition is gesture recognition. Significant research efforts have been made in that direction. As more notable, Sagayam and Hemanth have compiled a survey about the use of hand posture and gestures recognition [19]. In it, the authors describe the most effective research approaches as well as results from the recognition, decision trees, support vector machines, hidden Markov models, among others) can produce a 90+% recognition rate. In the paper, the authors have a special section dedicated to studying hand motion analysis (HMA), mentioning HMM and its variations as the most common way to analyze hand motion.

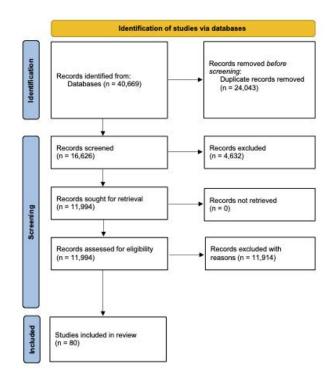
The gestural language signs differ from different countries, where, in 2020, the authors of [20] explored the recognition of Portuguese Sign Language. Several classifiers, including Deep Neural Network (DNN), Multilayer Perceptron (MLP), Support Vector Machines (SVM), Hidden Markov Models (HMM), and Subspace Gaussian Mixture Model (SGMM), were used for the classification of Portuguese Sign Language between 2021 and 2018, proving its reliability.

In [21], the authors presented a literature review related to gesture recognition in a mobile context as well as facial recognition in sign languages. The classification models used in the literature included SVM, Hierarchical Temporal Memory, Feedforward backpropagation neural network, Random-Forest, and MLP. The use of these devices makes feature extraction easier.

#### **III. METHODOLOGY**

This study adopted a scoping review methodology to identify and process the literature on sign language recognition, visualization, and interpretation published from January 2010 to September 2021. Using a scoping technique, we aimed to examine the research evidence in the broad field of technological solutions and sign languages, analyzing technology trends, including the resolved and emerging issues. The lack of a qualitative analysis of identified papers, the broad topic range, and the number of studies involved defined our approach as a scoping review and differentiated it from a systematic review [22], [23]. The purpose of this study fully complies with the aims of a scoping review "to search, select and synthesize the knowledge addressing an exploratory question to map key concepts, types of evidence, and research gaps", as defined in [24].

The methodological framework for scoping reviews proposed in [22] was adopted in this study, composed of five stages: Identification of a research question; Identification of relevant studies; Study selection; Charting the data; and Collating, summarizing, and reporting the results. The identification of relevant studies and study selection stages in the scoping review methodology corresponds to the "Preferred Reporting Items for Systematic Reviews and Meta-Analyses (PRISMA)" [25] workflow phases: study collection, scanning, and eligibility evaluation (see Fig. 1). Therefore, after the scoping review, our research identifies the relevant works according to the defined research questions and inclusion criteria and discusses them in more detail.



**FIGURE 1.** Flowchart of the PRISMA-based selection process.

#### A. RESEARCH QUESTIONS

The primary research questions of this review were defined as follows:

- RQ1 What are the prominent research topics and publication trends in literature?
- RQ2 In which way machine learning and deep learning algorithms can improve sign language recognition and interpretation?
- RQ3 Which approaches are most suitable for recognizing sequences of signs in sign language?

- RQ4 Is there any considerable difference in the state-of-theart in sign language recognition, visualization, and synthesis performance between different sign languages?
- RQ5 What are future research directions for computer translation between sign languages and written/spoken languages?

To answer these research questions, we performed an initial search and screening of papers and then selected the most relevant works and analyzed them in more detail. The following subsections describe the scoping review parameters, the search strategy, and the inclusion criteria.

#### **B. SCOPING REVIEW PARAMETERS**

This stage employs an NLP toolkit described in [26] enabling both automated search, scanning, and processing procedures. Its input parameters are a collection of search terms used to identify potentially relevant articles, the target digital libraries (i.e., Elsevier, Springer, IEEE, PubMed, and MDPI), and a set of properties that should be satisfied by the identified articles. To determine the initial pool of articles that are then evaluated for eligibility, we performed the search in the aforementioned digital libraries with the search phrases:

- "sign language recognition" OR
- "sign language synthesis" OR
- "sign language interpretation" OR
- "sign language linguistics" OR
- "sign language processing"

Keywords are search terms or phrases used to query a digital library (e.g., "sign language recognition "). First, eventual duplicates in the results are removed in a later phase. Then to evaluate whether an article is relevant to the research question, we define properties (see Fig. 2). Properties are words or phrases that are being searched in the title (i.e., text in italics in Fig. 2, such as "Sign language production"), abstract or keywords section of the articles identified with the keywords. Properties can also have synonyms (i.e., the comma-separated terms after the ones in italics, such as "sign language generation", which is a synonym of "sign language production"). Property groups are thematically, semantically, or otherwise grouped properties for a more comprehensive presentation of results in charts (e.g., text in bold in Fig. 2, such as "Domain-specific topics").

The start year indicates the starting year of publishing (inclusive) for the papers included in the study. The end year is the last year of publishing (inclusive) to be considered in the study. This review encompasses studies published from January 2010 to September 2021. The minimum of the relevant properties denotes the minimum number of properties that an article must contain to be considered suitable. This study set this value to 4, providing the right balance between falsely identifying relevant papers and potentially missing a relevant one.

When researchers perform a scoping review according to the methodology mentioned above, the actual tasks involve searching digital libraries with different search phrases, often involving complex Boolean conditions. The NLP toolkit

#### AI Topics:

- NLP, Natural language processing, Natural language understanding
- NLG, Natural language generation, language production
- NLU, Natural language understanding
- AI, Artificial Intelligence
- ML, Machine Learning
- DL, Deep Learning
- SVM, Support Vector Machines
- Ensemble Classifiers, XaBoost, XGBoost, GBT, GBTs, Gradient Boosted, random forest, extra trees, extremely randomized trees
- CNNs, Convolutional networks, Convolutional nets, Convolutional neural, CNN
- RNNs, Recurrent neural network, Recurrent nets, Recurrent neural, RNN
- HMMs, Hidden Markov Models, HMM
- NNs, Neural networks, Neural net, Neural nets, ANN, NNs, ANNs

#### Domain-specific topics:

- Visualization
- Recognition
- Depth Camera, Real Sense, Kinect, RGBD
- Spatial Analysis
- Spatial Synthesis
- Spatial Visualization, 3D Visualization, Three-dimensional visualization
- Sign Language Modelling
- Sign Language Production, Sign Language Generation
- Sign Language Recognition
- Image Analysis
- Video Processing, Image Processing

#### General Topics:

- Assistive Technologies
- 3D, Three-dimensional, Avatar
- Sign Language
- Deaf, Hearing Impaired

#### Study Type:

#### - Review

- Survey
- Randomized trial, Randomized control trial, Randomized controlled trial, RCT
- Clinical trial
- Observational study
- Cohort
- Experimental study

## FIGURE 2. Property groups, properties and synonyms used as search input.

counterpart to these phrases are the keywords described above. By screening the title and abstract, a reviewer determines whether the article is relevant to the study. The NLP toolkit is automated using the properties and synonyms to define what we are looking for in a report. Articles that contain more properties are considered more relevant. Undoubtedly, a human reader might better understand the context and better assess the relevance of an article. However, the NLP tool kit mimics these tasks in an automated and more thorough way, providing a higher efficiency in the scoping review process in far less time. For more information about the actual implementation, we refer the readers to [26].

#### C. SEARCH STRATEGY

The initial screening of duplicates and eligibility analysis was performed automatically using the aforementioned NLP-based toolkit utilizing Natural Language Processing (NLP) techniques, as described in [26]–[28].

The PRISMA methodology is described with details for our case in fig. 1 and it was used for the selection and processing of the collected research articles. Upon merging the results of multiple independent keyword-based searches, the collected papers were screened to remove duplicates. In addition, the screening process discarded articles that were not published in the required period or for which the title or abstract could not be analyzed due to parsing errors, unavailability, or other reasons.

The qualitative analysis of the remaining articles relied on the NLP toolkit that automates the initial steps in the PRISMA approach, significantly reducing the number of articles for manual evaluation. The identified articles were labeled as potentially relevant if they contained at least four predefined properties in their title or abstract (considering the above NLP-enhanced searching capabilities, thus performing a rough screening).

The NLP toolkit generates a spreadsheet file with the following fields: DOI (Digital Object Identifier), link, article title, authors, publication date, number of citations, abstract, keyword, source, publication title, affiliations, number of different affiliations, countries, number of different countries, number of authors, number of found property groups, and number of found properties. These additional properties aided the manual search of the articles with specific filtering criteria. Each of the articles in this reduced set was subsequently manually retrieved from their publisher and analyzed for potential inclusion in the qualitative and quantitative synthesis.

Finally, we used a more traditional systematic survey approach to provide a detailed analysis of the most relevant works per the previously mentioned topics. Five reviewers independently evaluated the remaining studies, and their suitability was determined with the agreement of all parties. Thus, the studies were evaluated per the previously defined eligibility criteria and the reviewers' evaluation of the study's relevance, quality, and impact.

## D. INCLUSION AND EXCLUSION CRITERIA

Considering the abundance of research available on this topic, we defined multiple inclusion criteria related to some qualitative properties of the articles, as follows:

- IC1 The articles should be written in English and should be published between 2010 and 2021, both inclusive;
- IC2 The sign languages treated in the article should be explicitly mentioned. It should contain at least one of the most common sign languages per Ethnologue [29] estimates (40 000 speakers or more). The list of languages includes, but it's not limited to: Indian, Pakistani, Brazilian, American, British, Mexican, Japanese, Russian, French and Chinese Sign language.<sup>2</sup> Publications that do not explicitly mention the sign language are excluded; Alternatively, if the research is sign language-independent, it should provide significant value in respect to IC3 and IC4.

<sup>&</sup>lt;sup>2</sup>Ethnologue does not give estimates of the speaker population of Chinese Sign Language, but it is included because of its perceived size.

- IC3 Articles related to sign language recognition are included if:
  - IC3a They describe the algorithms used (*e.g.* Hidden Markov Models, deep learning, convoluted neural networks, among others);
  - IC3b It has been tested on a publicly available data set, which is explicitly referenced;
  - IC3c The results are quantitatively described (*i.e.*, in terms of accuracy, F-score, among others);
- IC4 Articles related to sign language synthesis and visualization are included only if:
  - IC4a A successful visualization has been made, and the output has been qualitatively or quantitatively assessed by an expert or proficient sign language speaker (in that language);
  - IC4b The article discloses the used technology or device (*e.g.*, depth-enabled cameras, smartphones, Kinect, among others).

Considering that the screening part of the methodology was automated, there were cases when the potentially relevant articles were in fact not relevant based on the defined inclusion criteria above. Therefore, further manual inspection of the remaining articles (1856 as described below in the Results section), was key to identify whether the article should be included per the defined criteria above. Some of the works were included in the in the quantitative trends, but a minor subset was chosen for a more in-depth qualitative analysis.

#### **IV. RESULTS**

The funnel of article selection and screening is presented in Fig. 1. In the process of identification, 40,669 studies were deemed potentially relevant to the research field. Duplicates that emerged in the independent searches were removed, thus reducing the total number to 16,626 potentially relevant studies. The first screening process further eliminated 4632 studies outs, or if errors occurred while parsing or analyzing the title and abstract of the studies.

The remaining 11,994 studies underwent an automated eligibility assessment using advanced methods provided by the NLP toolkit [26]–[28]. After preprocessing, the articles were tagged with identified properties, and articles containing less than four properties were removed (i.e., 10,138 articles).

Of the remaining research publications, 1856) were deemed eligible for further manual inspection and inclusion in qualitative analysis. The statistics on the number of the collected articles, duplicates, articles with invalid time or the articles with incomplete data, and relevant articles are presented in Figure 3, for each digital library.

## A. STATISTICS PER DIGITAL LIBRARY

Regarding Fig. 3, the Springer digital library provides by far most of the potential candidates. However, after applying the additional PRISMA-defined filters based on the defined properties, the number of relevant articles is severely reduced, as visible in Fig. 4. This figure shows that most of the relevant

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articles for the defined research questions originate from IEEE Xplore.

The distribution of the number of collected and relevant articles per year is presented in Figure 5. From the chart, we can identify increasing research in the field, with a noticeable increase in the relevant research in time, with a small peak in 2014. However, the most relevant number of articles per the defined properties is in 2020.

Depending on the digital library, the ratio of the relevant papers containing specific keywords changes (as seen in Figure 6). For example, the Springer and IEEE digital library focus on technology-driven research into sign languages, with most studies published for sign language recognition and sign language visualization. Thus, it is a logical outcome of an engineering-based organization and publication. Springer has a similar tendency, although it does have a more general-purpose nature. PubMed shows a difference, recognizing as the most identified keyword, with a significant percentage of publications identified as sign language processing, linguistics, and interpretation. MDPI seems to have minor publications focused on this subject.

## **B. STATISTICS OF KEYWORD BASED QUERIES**

Selected keywords were used to map the literature corpus on sign language research. It is done concerning the set research questions that appear in the relevant articles with different distributions.

Regarding the source of relevant articles in relation to the search keywords, the trend is displayed in Fig. 6.

In figure 7 we have a distribution of the number of research publications that were identified with each keyword for the period January 2010 until September 2021. Here we present the annual number of research papers identified by the search engine of the three libraries with the defined keywords and additionally filtered manually based on their relevance to the specified properties. Please note that the internals of their search engines are not known, and the libraries might differ in the way they look for these keywords: only in the title, keywords section, abstract, or the whole article.

## C. EXTRACTION OF STUDY CHARACTERISTICS

The evaluated research studies are segmented into two tables. In Table 1, we have included the studies that have sign language recognition as the main research question. In the table, we present the research data in the following columns: *reference, year, key findings, test protocol, dataset, sign language, problem sub-type* and the *data input type* used for the publications. The column *key findings* summarises the most important parts of the publication, as well as the method that is being used to achieve the results. The *testing protocol* describes the training and testing phases (if present) in the paper. Next, the *dataset* column describes or references the data that is used for training or validating the results. The column *sign language* denotes the SL that is being used (if applicable). Next, the *problem sub-type* column describes whether the recognition is static, continuous,

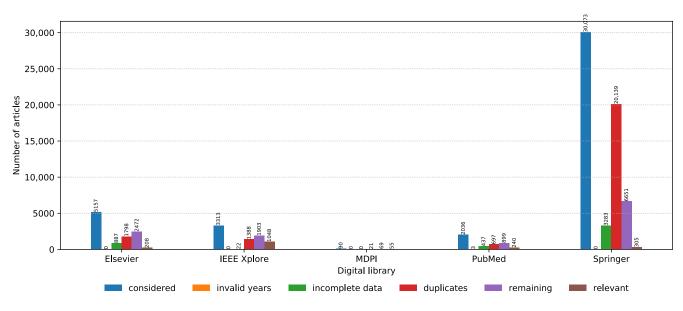


FIGURE 3. Number of articles (considered, rejected for various selection and eligibility issues, remaining, and relevant) per digital library.

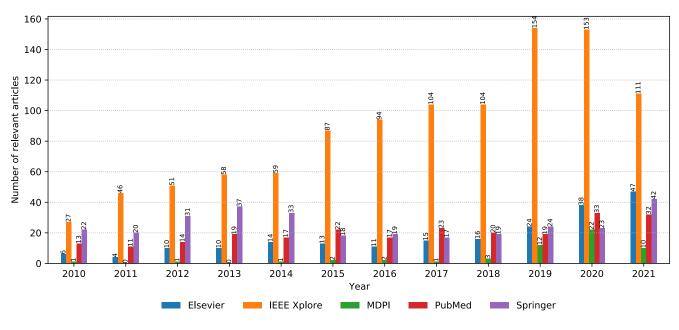


FIGURE 4. Number of identified relevant articles per year (2010-2021) per digital library.

isolated, etc. Finally, the *data input type* column shows the device used to capture input data.

(e.g., mostly engineering vs. medical), the availability of new devices and methods (e.g., the introduction of depth-based cameras, development of the machine learning field), etc.

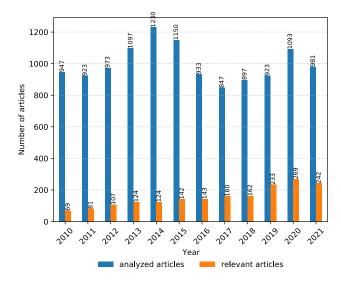
#### **V. DISCUSSION**

From Fig. 6 and Fig. 7 we can infer some interesting trends. The most active field for sign language research, indexed in the specified libraries, is sign language recognition, while sign language visualization and sign language processing are trailing behind.

This disparity in the number of publications can be attributed to multiple factors: the nature of the area of research

## A. EVOLUTION OF RESEARCH INTO SIGN LANGUAGES

One of the contributions of this study is categorizing the research around sign languages through the years. In the 1990s, most research related to sign languages was based on linguistic aspects (e.g., acquisition, evolution, teaching, analysis, etc.).



**FIGURE 5.** Number of analyzed and relevant articles in the span of 2010–2021.

#### 1) SIGN LANGUAGE ANALYSIS

When talking about the acquisition of sign languages, Volterra and Erting [30] published a book that compiled the most notable research studies about sign language acquisition for children of different ages and backgrounds. The amount of the presented research (21 research studies) enables the authors to establish correlations between sign languages and spoken languages. The most important conclusion is that children's stages when developing verbosity in sign and spoken language correspond to one another, and the acquisition phases are the same. Similar research was published by Boyes Braem [31] focusing on one deaf participant from deaf parents fluent in American sign language. Acquisition of sign languages by primates is also studied [32].

#### 2) CHALLENGES IN SIGN LANGUAGE RESEARCH

Due to the visual modality present in sign language research, several considerations have to be taken into account. When discussing sign language recognition, there is a distinction between isolated, single-sign recognition and recognising and interpreting sign language speech (continuous integration). Isolated recognition focuses on providing a specific term (e.g. noun, verb, adjective, etc.) to a visual image or sequence of images (in case of dynamic, motion based sign).

Sign language data can come from different sources, but usually take the form of:

- **image/sequence of images/videos** that have some form of color data (e.g. standard cameras).
- **transformation data** that can be acquired from specialized hardware like data gloves or through usage of motion-tracking techniques. Usually this data gives information for the movement (rotation and/or location of joints) of the arm and hands. The data is presented either as hierarchical transformations in respect to the

anatomy, or as raw transformation/joint pairings that need to be further processed.

• **depth data** that comes from specialized hardware that includes depth sensors. The most common input devices are Microsoft® Kinect<sup>TM</sup> (discontinued) and Intel® RealSense<sup>TM</sup> series of sensors. Kinect is better suited for whole-body movements and works best at larger distances (1-4 meters) while RealSense devices usually require closer distances (0.5 - 1.5 meters) from the sensors.

Some datasets can come with both image and depth data.

Also, the process of recognition for sign languages follows the standard pipeline for computer-vision based methodology. Ideally, when discussing any problem that needs to be processed from computer-vision perspective, it needs to follow the standard steps [17]:

- Acquisition. Acquisition of the data that is needed. In the case for sign language recognition, this includes gathering a specific set of images showing different signs under different conditions (e.g., lighting, environment, different people, etc.)
- **Preprocessing.** This can include various preprocessing tasks ranging from standardization of images taken from different devices to be in the same format, to different data augmentation techniques. Namely, to improve the robustness of the methods, this can include subtracting the per-channel mean pixel values calculated on the training dataset; random rescaling, horizontal flips, perturbations to brightness, contrast, and color, random cropping, etc.
- Segmentation. This involves the process of identifying and segmenting the relevant parts of the data (image), in this case, it would be image or video segments that are focusing on the hand gestures.
- Feature extraction. This process aims to create manageable sets of data that are derived from the initial raw data. This is usually done by reducing the raw data (a.k.a. dimensionality reduction), transformation to other color space, or extracting some custom properties that better describe certain aspects of the objects in the image, so that the classification is more robust and accurate.
- **Classification.** Categorize the input into a specific classes, in this case, recognizing different language symbols from the sign language gestures.

A driver to boost research into sign and gesture recognition was the ChaLearn competition held in 2012 [33] because of the dataset that was made available with it. The competition data set consisted of 50 000 gestures containing RGBD data, using the then-novel Microsoft Kinect sensor. The gestures recorded varied significantly, including signaling for drivers, aircraft, representing numerals, and sports referees. Here, the accompanying depth channel contributes considerably to the approaches taken by the competitors, although HMM-based methods dominate for the recognition of gestures.

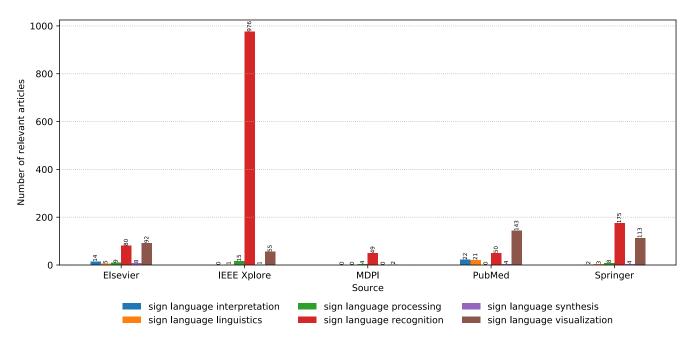


FIGURE 6. Distribution of the number of relevant articles with each of the defined keywords from each of the source publication databases.

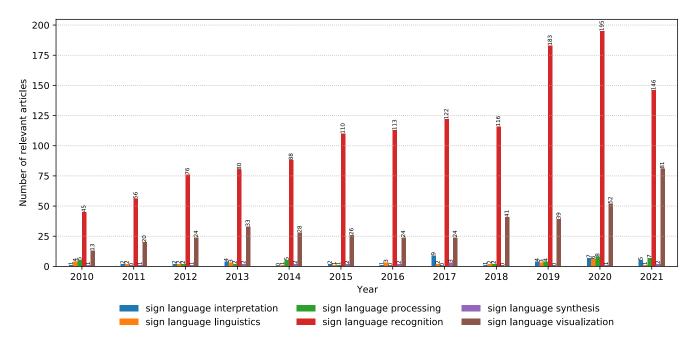


FIGURE 7. Distribution of the number of relevant articles with each of the defined keywords on the annual basis.

## 3) EDUCATION

The methodologies and results of education of Deaf people in different environments are studied and tested. It includes proposing training models for the education of deaf people, as well as sign language translators [34], [35], and the challenges of learning sign languages for in bilingual environment [36], as well as challenges in learning sign language [37].

## 4) MEDICAL ASPECTS

From a medical aspect, a lot of research has been conducted on the effect of various medical conditions on sign speaking and analyzing the neuro-biological aspects of sign languages. Most notable, cases of deaf patients that have acquired significant brain injuries and the effects on their communication have been investigated, with specifics on different conditions, like left [38], [39] and right hemisphere [40] damage. The research gave insight into the parts of the brain that are responsible for speech and signing. Further research, using functional MRI, has been used to figure out the parts of the brain that specialize in sign language communication [41], [42]. To summarize the research, a strong indication of independence of modality and language organization has been noticed.

#### 5) TECHNOLOGY ASPECT OF SIGN LANGUAGE STUDIES

The technology aspect of the research of sign languages can also be discussed as part of this analysis. Generally, computer science has more impact on sign language studies, providing mechanisms that vary from data-gathering to visualization.

## a: HCI TECHNOLOGIES

With the emergence of the human-computer interface (HCI) technology, some research into closely related areas to sign languages has been published. Schmauks and Wille [43] have hypothesized that in HCI, the motor responses, and especially facial expressions and hand gestures provide additional non-vocal information that needs to be taken into account when interfacing computer. Research into gesture recognition paved the road for developing sign language recognition as an emerging topic. Significant research of hand gesture recognition [44], [45] have foreseen as having an impact on sign language recognition. Bordegoni and Faconti [46] compared and outlined architectures for gesture recognition system, categorizing into two categories: data-based and pictorial-based, while the algorithms for recognition have been specified as based on pattern recognition, neural networks or statistical classification.

## **b:** IMPLEMENTED SYSTEMS

Authors of [47] did a similar analysis while additionally taking into account other modalities, such as head and eye movement. Gilbert *et al.* [47] also discuss and present implementation of the recognition system using Hidden Markov Models (HMMs), particularly ARGo and CADRE. This work also describes an implementation of a system for visualization (SAGA).

In 2001, a tool designed explicitly for linguistic, and computer vision research for American Sign Language was developed. The freely available tool, called SignStream [48], primarily was developed as annotation of multimedia content. Later versions of the tool utilize computer vision algorithms for the annotation of facial expressions and hand shapes. Ges-Rec3D [49] is a system developed primarily for augmentative and alternative communication for people that have a motor or speech disability. The system was designed to recognize arm-gestures using an electro-magnetic tracker (Polhemus).

Other systems such as the one presented in [50], [51], [52], [53] use gloves as sensors and machine learning approaches for detection and recognition of the sign letters. Some approaches even use Radio Frequency (RF) sensors to detect and recognise sign languages [54].

#### c: HMM-BASED METHODOLOGIES

In this phase (late 1990 - early 2000), various HMM recognition solutions are proposed. The most cited of all is the implementation of Waldherr *et al.* [55], where they create an autonomous helper robot that is controlled using gesture recognition based on implementing modified HMM based on the "Viterbi" algorithm. In 2003, Kai and Stiefelhagen [56] present another system for Human-Machine interaction using HMMs for detection of pointing gestures. In this system, the authors use a stereo camera to consider the position and orientation of the arm relative to the body. In their later work [57], Kai and Stiefelhagen additionally incorporate head motions in their recognition system. Kingsley and his coworkers [58] explored the possibility of developing context-sensitive HMM that would utilize the HMM for gesture learning and recognition.

## *d:* DEEP LEARNING BASED METHODS: TRANSFORMERS, 3D CNN AND OTHERS

The authors of [59] proposed an interactive alignment network with iterative optimization for weakly supervised continuous sign language recognition. It is composed of a 3D convolutional residual network for feature learning and classification with sequence modeling. However, it only focuses on using two decoders, such as Long short-term memory (LSTM) and connectionist temporal classification (CTC). The results demonstrated the effectiveness of the implemented decoders.

In [60], a deep learning-based pipeline architecture was proposed for automatic hand sign language recognition using Single Shot Detector (SSD), 2D Convolutional Neural Network (2DCNN), 3D Convolutional Neural Network (3DCNN), and LSTM from RGB input videos. The proposed model outperforms the state-of-the-art. It is an important study for the review presented in this paper because an automatic system was developed to recognize sign language.

The authors of [61] proposed a solution to speech sign language without previous knowledge of sign language. The proposed system converts these rotations through programming to vowels and consonants. Thus, computer vision is an important subject for the dissemination of sign language.

Transformers are superior in learning long-term dependency, hence the sign language Transformer model achieves remarkable progress in Sign Language Recognition (SLR) and Translation (SLT). The following works all report improvements over the state-of-the-art methods and they use different alternatives of transformer architectures.

Authors in [62] describe a method that improves state of the art results in gloss-to-text and video-to-text translation using STMC-Transformer that outperforms translation of GT glosses. Similarly, [63] proposes a Connectionist Temporal Classification (CTC) loss to bind the recognition and translation problems into a single unified architecture that does not require any ground-truth timing information, simultaneously solving two co-dependant sequence-to-sequence learning problems.

| Paper | Year | Key findings  | Test protocol   | Dataset   | Sign<br>Languages                                       | Problem<br>sub-type       | Data in-<br>put type |
|-------|------|---|---|---|---|---------------------------|----------------------|
| [65]  | 2022 | Word-level sign language recog-<br>nition based on the Transformer<br>model based on the estimation of<br>the pose of the human body in<br>the form of 2D landmark loca-<br>tions. WLASL, we are able to suc-<br>cessfully recognize 63.18% of sign<br>recordings in the 100-gloss sub-<br>set. For the 300-gloss sub-<br>set. For the 300-gloss sub-<br>set, we achieve recognition rate of 43.78%.<br>With the LSA64 dataset, we report<br>test recognition accuracy of 100%. | Introduce a robust pose nor-<br>malization scheme which<br>takes the signing space in<br>consideration and processes<br>the hand poses in a separate<br>local coordinate system, in-<br>dependent on the body pose.   | WLASL and LSA64   | American<br>Sign<br>Language                            | Isolated<br>recognition   | Video                |
| [66]  | 2021 | Propose a new model architecture<br>(PiSLTRc) with content-aware and<br>position-aware convolution layers<br>that explicitly select relevant fea-<br>tures using a neighborhood gather-<br>ing method. Then these features are<br>aggregated with position-informed<br>temporal convolution layers. Re-<br>ports state-of-the-art performance<br>improvement on translation quality<br>with +1.6 BLEU.  | The authors propose inject-<br>ing the relative position in-<br>formation to the attention<br>mechanism in the encoder,<br>decoder, and even encoder-<br>decoder cross attention.   | PHOENIX-2014,<br>PHOENIX-2014-T and<br>CSL  | German Sign<br>Language and<br>Chinese Sign<br>Language | Continuous<br>recognition | Video                |
| [50]  | 2021 | Authors use wearable capacitive<br>sensor to obtain signals. Authors<br>use Error Correction Output Code<br>Support Vector Machines (ECOC-<br>SVM) and K -Nearest Neigh-<br>bour (KNN) classifiers and obtain<br>99.50% and 97.94% average cross-<br>validation accuracy  | 800 data points consisting<br>15 features used for training<br>and the rest of the data for<br>test   | Special dataset created by<br>authors using the sensor  | American<br>Sign<br>Language                            | Static recog-<br>nition   | Glove                |
| [51]  | 2021 | A new real-time sign recognition<br>system based on a wearable and<br>low cost sensory glove or data<br>glove, which has 17 sensors with<br>65 channels, Results show ges-<br>ture recognition accuracies of 99%,<br>96% and 93.4% for numbers, al-<br>phabet letters and words.  | Validation on data collected<br>with the data glove for num-<br>bers, alphabet letters and<br>words   | Own dataset   | Malaysian<br>Sign<br>Language                           | Static recog-<br>nition   | Glove                |
| [64]  | 2020 | Applies a combination of feature<br>extraction using OpenPose for hu-<br>man keypoint estimation and end-<br>to-end feature learning with Con-<br>volutional Neural Networks. Au-<br>thors obtain an accuracy of 74.7%<br>on a vocabulary of 100 classes on<br>this dataset.  | The proven multi-head at-<br>tention mechanism used in<br>transformers is applied to<br>recognize isolated signs in<br>the Flemish Sign Language<br>corpus.   | Flemish sign language<br>(VGT) corpus   | Flemish Sign<br>Language                                | Isolated<br>recognition   | Video                |
| [76]  | 2020 | A novel deep learning method for<br>continuous sign language recog-<br>nition that applies a cross-modal<br>alignment between video and text<br>embeddings to better model the<br>intra-gloss dependencies in sign<br>language recognition. The pro-<br>posed method reports 24% WER<br>on the German and 2.4% WER on<br>the Chinese dataset.   | Train and test splits of the datasets.  | RWTH-Phoenix-Weather-<br>2014T, RWTH-Phoenix-<br>Weather-2014 and The<br>Chinese Sign Language<br>(CSL) dataset | German and<br>Chinese Sign<br>Language                  | Continuous<br>recognition | Video                |
| [60]  | 2020 | A model for hand sign recog-<br>nition using SSD, 3DCNN, and<br>LSTM from RGB. A hand skele-<br>ton is built using multi-view pro-<br>jections of 3D hand keypoints. A<br>new dataset is also presented. Re-<br>sults: 99.8% accuracy on RKS-<br>PERSIANSIGN and 91.12% accu-<br>racy on First-Person dataset 4.64%<br>hand pose estimation error on NYU<br>dataset.  | Evaluation of the proposed<br>model performed on two<br>datasets First-Person hand<br>action benchmark and RKS-<br>PERSIANSIGN, for hand<br>action recognition and hand<br>sign recognition. Also hand<br>pose estimation error on<br>NYU dataset. Five fold<br>cross-validation is used for<br>evaluation. | RKS-PERSIANSIGN<br>dataset presented in the<br>paper with 10,000 RGB<br>videos of 100 Persian sign<br>words     | Persian Sign<br>Language                                | Isolated<br>recognition   | Video                |

| [62] | 2020 | Improves state of the art results  | Translate GT gloss annota-  | PHOENIX-Weather 2014T  | German Sign                                  | Continuous                                      | Videos    |
|------|------|--|---|--|--|---|-----------|
|      |      | in gloss-to-text and video-to-<br>text translation using STMC-<br>Transformer that outperforms<br>translation of GT glosses.   | tions to simulate perfect to-<br>kenization on both datasets.<br>Then, perform video-to-text<br>translation on PHOENIX-<br>Weather 2014T with the<br>STMC-Transformer.  | and ASLG-PC12 corpus   | Language and<br>American<br>Sign<br>Language | recognition<br>and<br>translation               |           |
| [63] | 2020 | Uses a Connectionist Temporal<br>Classification (CTC) loss to bind<br>the recognition and translation<br>problems into a single unified ar-<br>chitecture.   | A joint approach that does<br>not require any ground-<br>truth timing information, si-<br>multaneously solving two<br>co-dependant sequence-to-<br>sequence learning problems<br>and leads to significant per-<br>formance gains.   | PHOENIX-Weather 2014T  | German Sign<br>Language                      | Continuous<br>recognition<br>and<br>translation | Video     |
| [54] | 2020 | Using RF sensors to recognise<br>signs. 72.5% accuracy in classifi-<br>cation of 20 native ASL signs.  | 3 deaf and 10 imitation<br>people included in the<br>experiment using predefined<br>scenario. Features extracted<br>from sensors for ADL and<br>sign classification and for<br>ASL sign classification.<br>Four 10GHz, One 24GHz<br>and one 77GHz sensors<br>used in the room. Both<br>single features, and fusion<br>of features is used with<br>various classification<br>algorithms. 75%, 25%<br>train-test split. | Special dataset for the pur-<br>poses of the experiment,<br>measurements made with<br>RF sensors and Kinect sen-<br>sor used for annotation  | American<br>Sign<br>Language                 | Continuous<br>recognition                       | RF sensor |
| [77] | 2020 | Sign Language Interpretation   | The authors developed a prototype to recognize sign language symbols.   | The authors demonstrate the<br>use of 8 surface Elec-<br>tromyography sensors to<br>identify the sign language.  | Chinese Sign<br>Language                     | Isolated recognition                            | Armband   |
| [59] | 2019 | A novel deep architecture based on<br>3D-ResNet and encoder-decoder<br>network with connectionist tempo-<br>ral classification by iterative opti-<br>mization for continuous SLR.  | In one setup 40 signers for<br>training and 10 for testing,<br>and in another setup 94 sen-<br>tences from different sign-<br>ers for training and 6 for<br>testing   | RWTH-Phoenix-Weather-<br>2014 dataset and The<br>Chinese Sign Language<br>(CSL) dataset which<br>contains 100 sentences<br>performed 5 times from 50<br>signers with 25000 videos<br>in total. It also provides<br>500 word isolated version | German and<br>Chinese Sign<br>Language       | Continuous<br>recognition                       | Video     |
| [78] | 2018 | Proposing an AI-based tool us-<br>ing convolutional neural networks<br>for language recognition with a<br>92.88% average recognition rate.   | Five subjects performed 200<br>hand signs recorded in 5<br>different viewing angles un-<br>der various background en-<br>vironments.  | Custom dataset.  | Indian Sign<br>Language                      | Isolated recognition                            | Video     |
| [79] | 2018 | Incorporating 18 new ASCII print-<br>able characters and three new fea-<br>tures, normalized distance between<br>direction extreme, close figure test,<br>and direction change ratio, of 15<br>dimensions to enhance the perfor-<br>mance of a system. The maximum<br>accuracy achieved using the com-<br>bination of existing and proposed<br>features is 96.95%. | Classifying the gestures<br>through a comparative<br>study.   | 58 gestures  | Gestures                                     | Isolated<br>recognition                         | Video     |
| [80] | 2018 | Sign Language Interpretation   | Describes a system for ac-<br>quisition and interpretation<br>of Indian sign language.  | The authors use portable<br>data gloves and an embed-<br>ded chip to capture and<br>interpret Indian sign lan-<br>guage.   | Indian Sign<br>Language                      | Continuous<br>recognition                       | Gloves    |
| [81] | 2017 | Using Convoluted Neural net-<br>works and Stacked de-noising<br>auto-encoder for audio recogni-<br>tion. Recognition CNN: up to 98%,<br>SDAE: up to 99.4%.   | Training: 1440 samples (im-<br>ages), Testing: 600 samples.   | PRIMA Moesland gesture<br>recognition DB   | American<br>Sign<br>Language                 | Static recog-<br>nition                         | Images    |

| [82] | 2017 | Presenting an SL recognition sys-  | Collecting and labeling  | n/a  | Chinese Sign                           | Isolated                  | Hand-                                    |
|------|------|--|--|--|--|---------------------------|--|
|      |      | tem using portable and cost-<br>affordable Leap Motion sensor and<br>applying kth-Nearest Neighbor (k-<br>NN) with high accuracy in static<br>sign language interpretation.  | 1000 sign gesture data<br>points for each gesture<br>before the accuracy test.   |  | Language                               | recognition               | tracking<br>device                       |
| [83] | 2017 | Proposing an MV3D-CNN process<br>applied to both real-world moving<br>vehicle recognition and sign lan-<br>guage recognition tasks has a good<br>performance.  | Labeling 22,300 two-view videos.   | Custom dataset of 50 signs.  | N/A                                    | Isolated recognition      | Video                                    |
| [8]  | 2017 | Presenting an SL recognition sys-<br>tem based on hand tracking devices<br>that utilize SVM for sign classifi-<br>cation and achieving up to 100%<br>accuracy  | Performing different evalua-<br>tions with over 50 individu-<br>als.   | American Sign Language<br>finger-spelling alphabet   | American<br>Sign<br>Language           | Static recog-<br>nition   | Hand-<br>tracking<br>device              |
| [84] | 2017 | Sign Language Visualization  | The paper describes a<br>method for generating<br>intermediate frames from<br>2D image(s) to create facial<br>expressions suitable for<br>sign language visualization<br>and synthesis.  | The research contributes<br>to creating intermediate<br>frames from the single<br>input image to generate<br>fluid facial gestures by<br>dividing the face model<br>into little triangles and<br>deforming them with affine<br>transformation. | Sign<br>language-<br>agnostic          | Visualization             | Video                                    |
| [85] | 2017 | Sign Language Visualization  | The authors successfully demonstrate the generation of sign language for weather forecast programs.  | This research discusses the<br>implementation of a sign<br>language caption system<br>using a 3D computer-<br>generated avatar.  | Korean Sign<br>Language                | Visualization             | Video                                    |
| [86] | 2016 | Identifying a new classifier<br>achieves an F1 score of 98%<br>when discriminating between<br>BSL and LSF videos with static<br>backgrounds and a 70% F1 score<br>when distinguishing between ASL<br>and BSL videos.   | Using half of each language<br>corpus for training and the<br>other half for testing.  | Dicta Sign corpus  | American &<br>British Sign<br>Language | Isolated<br>recognition   | Video                                    |
| [87] | 2016 | Presenting an SL recognition appli-<br>cation with Microsoft Kinect with<br>a 90% recognition rate for 13 signs<br>and 100% for 3 signs with an av-<br>erage accuracy rate of 90.68%.  | Using a vocabulary of 140<br>symbols collected by 18<br>subjects, totaling 5041 im-<br>ages.   | 140 symbols  | Indian Sign<br>Language                | Static recog-<br>nition   | Hand-<br>tracking<br>device<br>and Video |
| [88] | 2016 | Building a noise-free method for<br>classification during training, Se-<br>lective Temporal Filtering identi-<br>fies key feature vectors from a<br>noise-filtered input sequence.   | the proposed method not<br>only outperforms Condi-<br>tional Random Fields and<br>Hidden Markov Models in<br>noisy environments but also<br>in a well-controlled environ-<br>ment where we assume no<br>significant noise vectors ex-<br>ist | Synthetic-dataset and a<br>database of American Sign<br>Language   | American<br>Sign<br>Language           | Isolated<br>recognition   | Video                                    |
| [89] | 2016 | Extension on the research pre-<br>sented in [90] focused on embed-<br>ding a CNN into an HMM for<br>training and utilizing CNNs in a<br>Bayesian fashion for interpretation.<br>Improved upon previous research<br>for sign language recognition tasks<br>by between 15% and 38% relative<br>and up to 13.3% absolute. | The test protocol follows<br>the guidelines of SIGMA<br>and PHOENIX databases  | SIGNUM and PHOENIX<br>databases  | German Sign<br>Language                | Continuous<br>recognition | Video                                    |
| [91] | 2016 | Using LTSM and RNN for sign<br>language recognition. Depending<br>on the dataset in use, recognition<br>varies from 62% up to 86%.   | 25,000 samples from 50 dif-<br>ferent signers.   | Custom RGBD Kinect dataset.  | Chinese Sign<br>Language               | Isolated recognition      | Hand-<br>tracking<br>device              |
| [92] | 2016 | Testing three approaches on a data gloves-based system for wearable computing with the results showing the following accuracy: SVM 93%, Naive-Bayes 82.5%, and Decision trees 72.3%.   | Analyzing 56 data samples<br>from the custom glove   | Custom data  | Indian Sign<br>Language                | Isolated recognition      | Glove                                    |
| [93] | 2016 | Showcasing an SL recognition sys-<br>tem using the Leap motion con-<br>troller and recognition based on<br>NN multi-layer perception with an<br>average accuracy of 96.5%.   | Using a multi-layer percep-<br>tion neural network to ana-<br>lyze 520 samples of record-<br>ings  | Custom dataset   | American<br>Sign<br>Language           | Isolated recognition      | Hand-<br>tracking<br>device              |

| [90]  | 2015 | Perform continuous sign language<br>recognition across different sign-<br>ers on lab and real-life data.<br>Evaluation on SIGNUM database<br>(25 signers, 455 sign vocab-<br>ulary, 19k sentences) and un-<br>constrained "real-life" sign lan-<br>guage (RWTH-PHOENIX-Weather<br>database: 9 signers, 1081 sign vo-<br>cabulary, 7k sentences) and achieve<br>up to 10.0%/16.4% and respec-<br>tively up to 34.3%/53.0% word<br>error rate for single signer/multi-<br>signer setups. | The test protocol follows<br>the guidelines of SIGMA<br>and PHOENIX databases   | SIGNUM and PHOENIX<br>databases   | German Sign<br>Language      | Continuous<br>recognition | Video  |
|-------|------|--|---|---|------------------------------|---------------------------|--------|
| [94]  | 2013 | Using an early combination of<br>features, the late fusion of deci-<br>sions, and synchronous combina-<br>tion on the hidden Markov model<br>state level and asynchronous com-<br>bination on the gloss level to<br>achieve the best-published word er-<br>ror rate on the SIGNUM database,<br>10.7% and the RWTH-PHOENIX<br>database, 41.9%.  | The test protocol follows<br>the guidelines of SIGMA<br>and PHOENIX databases   | SIGNUM and PHOENIX<br>databases   | German Sign<br>Language      | Isolated<br>recognition   | Video  |
| [95]  | 2013 | Using Hu-moment pattern match-<br>ing for classification of signs via<br>image recognition.  |   | ALS alphabet images   | American<br>Sign<br>Language | Static recog-<br>nition   | Images |
| [96]  | 2013 | Presenting a novel algorithm for<br>hand recognition using image pro-<br>cessing and exploring its applica-<br>tion in security-based systems by<br>testing for different gestures with<br>an accuracy rate of 95.2%.  | Implementing the algorithm<br>in MATLAB programming<br>language and testing on<br>over 50 samples.  | Custom dataset.   | Gestures                     | Static recog-<br>nition   | Images |
| [97]  | 2013 | Proposing a real-time system that<br>recognizes emotions from body<br>movements data streams with an<br>accuracy of 72%.   | Using the MoCap UCLIC<br>affective gesture database<br>for training the classifier,<br>then testing the trained<br>classifier with different<br>subjects using continuous<br>Kinect data. | 27 postural features  | Gestures                     | Continuous<br>recognition | Video  |
| [98]  | 2012 | Comparing the performance of<br>DTW and HMM methods using<br>different criteria shows that DTW<br>has higher performance.  | Analyzing a set of recorded gestures.   | A custom dataset that in-<br>cludes a multitude of sam-<br>ples from ten different ges-<br>tures.                 | N/A                          | Isolated recognition      | Video  |
| [99]  | 2012 | Proposing a cost-effective and non-<br>intrusive web-cam SL recogni-<br>tion system that allows for multi-<br>language training and recognition.<br>Experimental results show the sys-<br>tem works well for dialect-free sign<br>language translation with an aver-<br>age recognition accuracy between<br>55% and 65%.   | Using a sample set of 90<br>images to train the numeric<br>neural network and a col-<br>lection of 240 pictures to<br>train the neural network for<br>alphabet characters.                | Custom dataset.   | English to<br>Spoken         | Static recog-<br>nition   | Images |
| [100] | 2012 | Comparing the performance of Lo-<br>cal Binary Patterns with geometric<br>moments describing the trajectory<br>and shape of hands. When features<br>are combined, the recognition rate<br>increases to 99.75% for signer de-<br>pendent tests and 57.54% for inde-<br>pendent signer tests.  | Testing the recognition per-<br>formance of individual fea-<br>tures and their combinations<br>with several repetitions.  | 23 signs  | Gestures                     | Static recog-<br>nition   | Images |
| [101] | 2012 | Sign Language Visualization  | Introduces a computing<br>model that is trained to<br>provide better interpolation<br>between words.  | The research contributes to<br>creating more accurate and<br>intelligible synthesized sign<br>language animation. | Chinese Sign<br>Language     | Visualization             | N/A    |
| [102] | 2011 | Presenting a simple SL recognition<br>system that utilizes skin color seg-<br>mentation and neural networks to<br>achieve a recognition accuracy rate<br>of 92.58%.  | Training the network with 60 % of samples and testing with the remaining 40 % to classify the right and left-hand signs.  | A dataset with 3080 feature vectors.  | N/A                          | Static recog-<br>nition   | Images |

|       | 2011 | They analyze a system consist-       | Testing the system with 26     | Custom dataset.               | N/A          | Static recog- | Images     |
|-------|------|--------------------------------------|--------------------------------|-------------------------------|--------------|---------------|------------|
| [103] |      | ing of three components: real-time   | different gestures to evalu-   |                               |              | nition        |            |
|       |      | hand tracking, hand-tree construc-   | ate the effectiveness of the   |                               |              |               |            |
|       |      | tion, and hand gesture recognition.  | proposed approach.             |                               |              |               |            |
|       |      | The results show that the clas-      |                                |                               |              |               |            |
|       |      | sification ability of single-layered |                                |                               |              |               |            |
|       |      | CVNN on unseen data is compara-      |                                |                               |              |               |            |
|       |      | ble to the conventional real-valued  |                                |                               |              |               |            |
|       |      | neural network (RVNN) having         |                                |                               |              |               |            |
|       |      | one hidden layer.                    |                                |                               |              |               |            |
|       | 2011 | Presenting a human-robot interac-    | Eight compound gestures        | N/A                           | Gestures     | Continuous    | Video      |
| [104] |      | tion system that recognizes mean-    | are employed in the system,    |                               |              | recognition   |            |
|       |      | ingful gestures composed of con-     | each assigned to a motion      |                               |              |               |            |
|       |      | tinuous hand motions in real-time    | or functional control com-     |                               |              |               |            |
|       |      | based on hidden Markov mod-          | mand.to allow users to op-     |                               |              |               |            |
|       |      | els achieving an average gesture     | erate an autonomous robot      |                               |              |               |            |
|       |      | recognition rate of 96%.             | efficiently.                   |                               |              |               |            |
|       | 2010 | Presenting an application for learn- | Using the assigned proto-      | Georgia Tech Gesture          | American     | Isolated      | gloves and |
| [105] |      | ing ASL that uses data gloves        | col for Georgian Tech Ges-     | Recognition Toolkit           | Sign         | recognition   | video      |
|       |      | and video for sign acquisition and   | ture Recognition Toolkit for   |                               | Language     |               |            |
|       |      | HMM for verification with a recog-   | HMM training                   |                               |              |               |            |
|       |      | nition rate up to 81.7%.             |                                |                               |              |               |            |
|       | 2010 | Using two approaches, Euclidean      | Using a repository of many     | 22 specific kinds of ISL      | Indian Sign  | Static recog- | Images     |
| [106] |      | distance, and K-nearest neighbor     | images to train and test sam-  | class/word                    | Language     | nition        |            |
|       |      | metrics, SL recognizes many signs    | ples under various light illu- |                               |              |               |            |
|       |      | classified with a direction his-     | mination conditions.           |                               |              |               |            |
|       |      | togram.                              |                                |                               |              |               |            |
|       | 2010 | Sign Language Visualization          | Prototype design of an         | The authors demonstrate a     | Italian Sign | Visualization | N/A        |
| [107] |      |                                      | avatar for sign language       | prototype 3D virtual charac-  | Language     |               |            |
|       |      |                                      | visualization.                 | ter for visualizing sign lan- |              |               |            |
|       |      |                                      |                                | guages.                       |              |               |            |

Another transformer-based approach is presented in [64], which proposes a combination of feature extraction using OpenPose for human keypoint estimation and end-to-end feature learning with Convolutional Neural Networks, using the proven multi-head attention mechanism used in transformers. Another transformer-based approach applied in word-level recognition is presented in [65].

The authors of [66] propose a transformer model with selfattention mechanism. It proposes the use of content-aware and position-aware convolution layers that explicitly select relevant features using a neighborhood gathering method.

#### e: RECOGNITION USING DECOMPOSITION

In-Cheol and Sung [67] utilized HMMs to create a data-glove-based sign language recognition system using the Polhemus gloves. The algorithm focused on decomposing gestures into primitive strokes, using different HMMs for gesture decomposition and stroke recognition. In its limited experiments, the algorithm achieved a high level of recognition rate (96.88%). Decomposition of gestures, along with linguistic knowledge system, was also used by Konstantinos *et al.* [68]. Here, the authors decompose the image sequences into primitives: handshape, location, and movement. Later, they use linguistic knowledge to recognize the ASL speech. They used this technique on a large set of signs and achieved between 86 and 97.13 percent accuracy.

When directly speaking about sign languages, protosystems based on neural networks for sign language recognition also emerge. For example, Kim *et al.* [69] are credited for creating a recognition system for Korean sign language based on input generated from data-hand gloves. In 2000, Marcus and his colleagues [70] presented a Neural Network (NN), called T-CombNET, that has been specialized in hand recognition. They tested the network using signs from Japanese fingerspelling and achieved up to 96.5% recognition when using dynamic gestures. Ming and Naendra [71] created a sequential image-based neural network that is capable of recognition of hand-trajectory gestures by utilizing and decomposing the image sequences. The NN was tested for recognition of 40 gestures from American Sign Language.

Fuzzy-rule approaches were also considered and were tested on Taiwanese sign language [72]. Similar fuzzy-based methods were considered and tested for Brazilian sign language [73].

#### **B. VISUALIZATION**

From the sign language visualization aspect, efforts were made to simplify the description of the models used for gesture/sign language visualization. Aside from the proposed system by Gibert *et al.* [47], general improvements of the more subtle aspects of sign language visualization. John McDonald *et al.* [74] purposefully created an anatomically correct 3D model and skeleton of a human hand for use with American Sign Language animation and visualization.

#### C. NOTATION SYSTEMS

The computer representation of sign language notation was discussed in [75]. The paper details the then-known sign

language notation systems: Stokoe Notation and its derivative, the BSL notation; SignFont and HamNoSys. The authors conclude that the then-current notation systems are not sufficient for sign language and propose a new type of notation that considers three-layered notation based on: "idea", "word", and " deed".

#### D. LIMITATIONS OF THE APPROACH

This study considered only three digital libraries, and some relevant articles from other indexed publishers were not considered. However, keeping in mind the size of the evaluated digital libraries, we believe that the obtained results are representative and in line with the study's goals. All digital libraries used in this work have different internal search engines with different rules for the maximum number of papers retrieved and another formatting of search results. The papers obtained for this study were obtained from the various search engines using the same search queries. However, keeping in mind the number of papers analyzed within this review, we believe that specificities of the publishers' search engines have limited impact and have not influenced the findings of this work. In the future, the NLP tool kit needs to be extended to process more digital libraries. In addition, there is an apparent need for a Web app that will make it available to a broader audience. Until then, readers are encouraged to contact the authors if they are interested in using the toolkit.

#### **VI. CONCLUSION**

The specific problems tackled in this research occupy a wide range of topics connected to sign language research. The main problem when working with sign language is to effectively translate and interpret them into some easily comprehensible form, both for people and machines. To do this the researchers have to adjust to the visual modality of sign languages and extract key features from the visual data. This problem includes recognition of static images, sequences of images (video) as well as other types of information (e.g., depth data).

Based on the thorough analysis of the selected publication, we can conclude that machine learning and deep learning algorithms can improve sign language recognition and interpretation.

This means that sign language recognition systems depend on machine learning approaches that are typical for other problem domains. These approaches include pattern recognition, statistical approaches, and neural network-based approaches. Historically HMMs gave the best results initially since they, as an algorithm, seem to be most suitable for time series data. However, lately, neural network-based approaches and deep learning approaches seem to give better results. Among them, approaches based on 3D-CNN, Transformer and LSTM architectures seem to dominate the continuous sign language recognition regardless of the sign language. We can attribute the 3DCNN approach due to its success with problems with image/video recognition, time series, and natural language processing, areas that we explained that are of interest in sign language research. Similarly, LSTMs are used due to their effectiveness with timeseries data.

Additional studies need to be performed to analyze different sign languages' recognition, visualization, and synthesis performance. Most of the studies compare the more novel approaches to the traditional methods for the same language, but there is a lack of studies that compare methods between different languages. This is due to the fact that there are lack of datasets of translated sign language sequences. Nevertheless, based on our review of the existing literature, one can conclude that the state-of-the-art approaches used for sign language recognition perform similarly for various languages. Therefore, the same methods with slight modification are applied to different sign languages with similar success.

With the improvement of the hardware and the machine learning approaches, including the advancements of neural networks and deep learning, one can expect that there will be a significant improvement in all technologies for sign language recognition and visualization. The current limitations are usually related to a lack of data and training examples for all languages. However, this limitation is becoming less and less relevant with the advancements of the transfer learning approaches. Therefore, we expect that within the following five to ten years, there will be public and commercial products that will perform live translation from and to distinct sign languages. This will ideally allow for real-time communication between people that use different modalities (sign language and vocal speech) as well as developing systems that will translate speech from one sign language to another.

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