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### THE WEIGHTED DIAPHONY

#### V. Ristovska, V. Grozdanov

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#### Abstract

In the present paper the authors introduce a new quantitative measure for uniform distribution of sequences in  $[0, 1)^s$ , the so-called "weighted diaphony." The definition of the weighted diaphony is based on using the trigonometric functional system. At a special choice of the parameters  $\alpha$  and  $\gamma$  on which the weighted diaphony depends, the "classical" diaphony introduced by Zinterhof is obtained. It is shown that the computing complexity of the weighted diaphony of an arbitrary net composed of N points in  $[0,1)^s$  is  $\mathcal{O}(S.N^2)$ . Relationship between the worst-case error of the quasi-Monte Carlo integration in a class of weighted Hilbert space and the weighted diaphony is obtained.

Key words and phrases: weighted diaphony, diaphony, worst-case error **2000 Mathematics Subject Classification:** 65C05, 11K38, 11K06

1. Introduction. Let  $s \ge 1$  be a fixed integer and  $\xi = (\mathbf{x}_n)_{n\ge 0}$  is an arbitrary sequence of points in the s-dimensional unit cube  $[0,1)^s$ . For an arbitrary subinterval  $J \subseteq [0,1)^s$  with a volume  $\mu(J)$  and an arbitrary integer  $N \ge 1$  we denote with  $A_N(\xi; J)$  the number of the points of the sequence  $\xi$  which indices n satisfy  $0 \le n \le N-1$  and belong to the interval J. The sequence  $\xi$  is called uniformly distributed if the equality  $\lim_{N\to\infty} N^{-1}A_N(\xi; J) = \mu(J)$  holds for every subinterval J of  $[0,1)^s$ . The examination of numerical measures for distribution of sequences in  $[0,1)^s$  is of

The examination of numerical measures for distribution of sequences in  $[0, 1)^s$  is of interest of the quantitative theory of the uniform distribution of sequences. In general the discrepancy and the diaphony are quantitative measures for the irregularity of the distribution of sequences in  $[0, 1)^s$ .

Let  $\mathcal{T} = \{\exp(2\pi \mathbf{i} \langle \mathbf{m}, \mathbf{x} \rangle) : \mathbf{m} = (m_1, \dots, m_s) \in \mathbf{Z}^s, \mathbf{x} = (x_1, \dots, x_s) \in [0, 1)^s, \langle \mathbf{m}, \mathbf{x} \rangle = \sum_{j=1}^s m_j x_j \}$  be the trigonometric functional system. ZINTERHOF [1] introduces the "classical" diaphony as a numerical measure for distribution of sequences in  $[0, 1)^s$ . For each integer  $N \geq 1$  the diaphony  $F_N(\mathcal{T}; \xi)$  of the first N elements of the sequence  $\xi = (\mathbf{x}_n)_{n>0}$  in  $[0, 1)^s$  is defined as

$$F_N(\mathcal{T};\xi) = \left(\sum_{\mathbf{m}\in\mathbf{Z}^s,\mathbf{m}\neq\mathbf{0}} R^{-2}(\mathbf{m}) \left| \frac{1}{N} \sum_{n=0}^{N-1} \exp(2\pi \mathbf{i}\langle\mathbf{m},\mathbf{x}_n\rangle) \right|^2 \right)^{\frac{1}{2}},$$

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where for each vector  $\mathbf{m} = (m_1, \ldots, m_s) \in \mathbf{Z}^s \ R(\mathbf{m}) = \prod_{j=1}^s \max(1, |m_j|).$ 

For multivariate numerical integration SLOAN and WOŽNIAKOWSKI [<sup>2</sup>] propose to arrange the coordinates  $x_1, x_2, \ldots, x_s$  of the functions which are integrated and respectively the coordinates of the nets which we use in the process of the numerical integration in such a way that  $x_1$  is the most important coordinate,  $x_2$  is the next one, and so on. This is realized by associating nonincreasing weights  $\gamma_1, \gamma_2, \ldots, \gamma_s$  to the successive coordinate direction. Following Sloan and Wožniakowski we will recall the concept for the weighted  $\mathcal{L}_2$  discrepancy. For an arbitrary sequence  $\xi$  of points in  $[0, 1)^s$  and an arbitrary integer  $N \ge 1$ , define the discrepancy function as  $\Delta_N(\xi; \mathbf{t}) =$  $N^{-1}A_N(\xi; [0, t_1) \times \cdots \times [0, t_s)) - t_1 \dots t_s$ , where for  $1 \le j \le s t_j \in [0, 1)$  and  $\mathbf{t} =$  $(t_1, \dots, t_s)$ .

Let D denote the index set  $D = \{1, 2, ..., s\}$ . For an arbitrary subset  $u \subseteq D$  let |u| be the cardinality of u. For a vector  $\mathbf{x} = (x_1, x_2, ..., x_s) \in [0, 1)^s$  let  $\mathbf{x}_u$  denote the vector from  $[0, 1)^{|u|}$  containing all components of  $\mathbf{x}$ , whose indices are in u. We denote  $d\mathbf{x}_u = \prod_{j \in u} dx_j$ . Let  $(\mathbf{x}_u, \mathbf{1})$  be the vector from  $[0, 1)^s$  with components  $x_j$  if  $j \in u$  and components 1 if  $j \notin u$ .

For a given vector of weights  $\boldsymbol{\gamma} = (\gamma_1, \gamma_2, \dots, \gamma_s)$ , where  $\gamma_1 \geq \gamma_2 \geq \dots \geq \gamma_s > 0$ and nonempty  $u \subseteq D$  we put  $\boldsymbol{\gamma}_u = \prod_{j \in u} \gamma_j$ . Then the weighted  $\mathcal{L}_2$  discrepancy of the first N elements of the sequence  $\boldsymbol{\xi}$  is defined as

$$\mathcal{L}_{2,\boldsymbol{\gamma},N}(\xi) = \left(\sum_{\emptyset \neq u \subseteq D} \boldsymbol{\gamma}_u \int_{[0,1)^{|u|}} \Delta_N^2(\xi; (\mathbf{x}_u, \mathbf{1})) d\mathbf{x}_u \right)^{\frac{1}{2}}.$$

The aims of this research are:

- To define a new version of the diaphony, the so-called "weighted diaphony" and to prove that the weighted diaphony is a quantitative measure for uniform distribution of sequences in  $[0, 1)^s$ .
- To show that from the weighted diaphony definition at a special choice of the parameters on which it depends the "classical" diaphony is obtained.
- To show that the computing complexity of the weighted diaphony of an arbitrary net, composed of N points in  $[0, 1)^s$ , is  $\mathcal{O}(S.N^2)$ .
- To obtain the relationship between the worst-case error of the integration in the weighted Hilbert space  $H_{s,\alpha,\gamma}$  (see Section 3) which is based on using determined nets in  $[0,1)^s$  and the weighted diaphony of these nets.

2. Statement of the results. In order to give the form of the so-called "weighted diaphony" (see Definition 1), the parameters  $\alpha$  and  $\gamma$  will be used. To characterize the importance of the different coordinates of the nets in  $[0,1)^s$  the parameters (or "weights")  $\gamma = (\gamma_1, \gamma_2, \ldots, \gamma_s)$ , where  $\gamma_1 \geq \gamma_2 \geq \cdots \geq \gamma_s > 0$  will be used. The fixed real number  $\alpha > 1$  will characterize the rate of decay of the Fourier coefficients of a special function  $G(\alpha, \gamma; \cdot)$  constructed in Theorem 2. This function will play an important role in defining the weighted diaphony. In the next definition we will give the concept of the weighted diaphony:

**Definition 1.** Let  $\alpha \geq 2$  be an arbitrary even integer and  $\gamma = (\gamma_1, \gamma_2, \ldots, \gamma_s)$ , where  $\gamma_1 \geq \gamma_2 \geq \cdots \geq \gamma_s > 0$  is an arbitrary vector of real weights. For each integer

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 $N \geq 1$  the weighted diaphony  $F_N(\mathcal{T}; \alpha, \gamma; \xi)$  of the first N elements of the sequence  $\xi = (\mathbf{x}_n)_{n>0}$  of points in  $[0,1)^s$  is defined as

$$F_N(I;\alpha,\gamma;\xi) = \left(\frac{1}{\prod_{j=1}^s [1+2\gamma_j\zeta(\alpha)] - 1} \sum_{\mathbf{m}\in\mathbf{Z}^s, \mathbf{m}\neq\mathbf{0}} r(\alpha,\gamma;\mathbf{m}) \left|\frac{1}{N} \sum_{n=0}^{N-1} \exp(2\pi \mathbf{i}\langle\mathbf{m},\mathbf{x}_n\rangle)\right|^2\right)^{\frac{1}{2}},$$

where for each vector  $\mathbf{m} = (m_1, \ldots, m_s) \in \mathbf{Z}^s$  the coefficient  $r(\alpha, \gamma; \mathbf{m})$  is defined as  $r(\alpha, \gamma; \mathbf{m}) = \prod_{j=1}^{s} r(\alpha, \gamma_j; m_j)$  and for an arbitrary real  $\gamma > 0$  and integer m we define

$$r(\alpha, \gamma; m) = \begin{cases} 1, & \text{if } m = 0, \\ \frac{\gamma}{m^{\alpha}}, & \text{if } m \neq 0, \end{cases}$$

and  $\zeta(\alpha)$  is the well-known Riemann's zeta-function.

**Theorem 1.** The sequence  $\xi$  of points in  $[0,1)^s$  is uniformly distributed if and only if the equality

$$\lim_{N\to\infty}F_N(\mathcal{T};\alpha,\boldsymbol{\gamma};\xi)=0$$

holds for each even integer  $\alpha \geq 2$  and for an arbitrary vector  $\gamma$  of positive weights. From the point of view of the practical application of the weighted diaphony we note the following: for each integer  $N \geq 1$  and an arbitrary sequence  $\xi$  of points in  $[0,1)^s$  the inequalities

(1) 
$$0 \le F_N(\mathcal{T}; \alpha, \gamma; \xi) \le 1$$

have to hold for each even integer  $\alpha \geq 2$  and an arbitrary vector  $\gamma$  of positive weights. The multiplier  $(\prod_{j=1}^{s} [1+2\gamma_j\zeta(\alpha)]-1)^{-1}$  guarantees that the inequalities (1) hold.

For each integer  $N \ge 1$  and an arbitrary sequence  $\xi$  of points in  $[0,1)^s$  from the Definition 1 at the special choice of the parameters  $\alpha = 2$  and  $\gamma = \mathbf{1} = (\mathbf{1}, \dots, \mathbf{1})$  we obtain the equality  $\sqrt{\left(1+\frac{\pi^2}{3}\right)^s - 1} \cdot F_N(\mathcal{T}; 2, \mathbf{1}; \xi) = F_N(\mathcal{T}; \xi)$ , i.e. the "classical" di-

aphony  $F_N(\mathcal{T};\xi)$  of the sequence  $\xi$  with an exactness of the multiplier  $\sqrt{\left(1+\frac{\pi^2}{3}\right)^s-1}$ is obtained from Definition 1.

**Lemma 1.** For arbitrary integer numbers  $\mu$  and h such that  $0 \le h \le \mu$  let us define the coefficients  $\varkappa(\mu, h) = -\frac{\mu!}{(\mu+1-h)!}$ . Let  $\alpha \ge 2$  be an arbitrary and fixed integer and let  $\gamma > 0$  be an arbitrary real. We introduce the matrices

$$K(\alpha) = \begin{bmatrix} \varkappa(0,0) & \varkappa(1,0) & \varkappa(2,0) & \dots & \varkappa(\alpha-1,0) & \varkappa(\alpha,0) \\ 0 & \varkappa(1,1) & \varkappa(2,1) & \dots & \varkappa(\alpha-1,1) & \varkappa(\alpha,1) \\ 0 & 0 & \varkappa(2,2) & \dots & \varkappa(\alpha-1,2) & \varkappa(\alpha,2) \\ \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & \dots & \varkappa(\alpha-1,\alpha-1) & \varkappa(\alpha,\alpha-1) \\ 0 & 0 & 0 & \dots & 0 & \varkappa(\alpha,\alpha) \end{bmatrix}$$

and  $B(\alpha, \gamma) = [-1, 0, \dots, 0, \gamma \cdot (2\pi \mathbf{i})^{\alpha}]^T$ , where the matrix  $B(\alpha, \gamma)$  is with  $\alpha + 1$  elements.

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(i) We define the functions  $\phi(\alpha, j)$  as:  $\phi(\alpha, \alpha) = \frac{-1}{\alpha!}$  and for  $j = \alpha - 1, \alpha - 2, \dots, 1, 0$  $\phi(\alpha, j) = \frac{1}{j!} \sum_{h=j+1}^{\alpha} \varkappa(h, j) \phi(\alpha, h)$ . Then the solution  $C = [C_0, C_1, \dots, C_{\alpha}]^T$  of the system  $K(\alpha) \cdot C = B(\alpha, \gamma)$  is given in the form  $C_0 = 1 + \phi(\alpha, 0) \gamma(2\pi \mathbf{i})^{\alpha}$  and for  $1 \leq j \leq \alpha C_j = \phi(\alpha, j) \gamma(2\pi \mathbf{i})^{\alpha}$ .

(ii) For the solution of the system  $K(\alpha) \cdot C = B(\alpha, \gamma)$  we obtain some partial results:  $C_{\alpha} = -\frac{(2\pi i)^{\alpha}\gamma}{\alpha!}, C_{\alpha-1} = \frac{(2\pi i)^{\alpha}\gamma}{(\alpha-1)!2}, C_{\alpha-2} = -\frac{(2\pi i)^{\alpha}\gamma}{(\alpha-2)!12}, C_{\alpha-3} = 0, C_{\alpha-4} = \frac{(2\pi i)^{\alpha}\gamma}{(\alpha-4)!720}, C_{\alpha-5} = 0, C_{\alpha-6} = -\frac{(2\pi i)^{\alpha}\gamma}{(\alpha-6)!}, C_{\alpha-7} = 0, C_{\alpha-8} = \frac{(2\pi i)^{\alpha}\gamma}{(\alpha-8)!}, C_{\alpha-9} = 0, C_{\alpha-10} = -\frac{(2\pi i)^{\alpha}\gamma}{(\alpha-6)!}, C_{\alpha-12} = \frac{(2\pi i)^{\alpha}\gamma}{(\alpha-12)!}, C_{\alpha-13} = 0.$ 

**Lemma 2.** Let  $\alpha \geq 2$  be an arbitrary fixed even integer.

(i) For an arbitrary real  $\gamma > 0$  let us construct the polynomial

$$g(\alpha, \gamma; x) = C_{\alpha} x^{\alpha} + C_{\alpha-1} x^{\alpha-1} + \dots + C_1 x + C_0, \quad x \in [0, 1),$$

where  $C = [C_0, C_1, \ldots, C_{\alpha}]^T$  is the solution of the system  $K(\alpha) \cdot C = B(\alpha, \gamma)$ . Then for each integer *m* the Fourier coefficient  $\widehat{g}(\alpha, \gamma; m)$  of the polynomial  $g(\alpha, \gamma; \cdot)$  satisfies the equality  $\widehat{g}(\alpha, \gamma; m) = r(\alpha, \gamma; m)$ , where the coefficient  $r(\cdot)$  is defined in Definition 1.

(ii) Let  $\gamma = (\gamma_1, \gamma_2, \dots, \gamma_s)$ , where  $\gamma_1 \geq \gamma_2 \geq \dots \geq \gamma_s > 0$  is an arbitrary vector of weights. For  $1 \leq j \leq s$  let  $B(\alpha, \gamma_j) = [-1, 0, \dots, 0, \gamma_j \cdot (2\pi \mathbf{i})^{\alpha}]^T$  and  $C_j = [C_0^{(j)}, C_1^{(j)}, \dots, C_{\alpha}^{(j)}]^T$  are the solutions of the systems  $K(\alpha) \cdot C_j = B(\alpha, \gamma_j)$ . For  $1 \leq j \leq s$  we define the polynomials  $g(\alpha, \gamma_j; x) = C_{\alpha}^{(j)} x^{\alpha} + C_{\alpha-1}^{(j)} x^{\alpha-1} + \dots + C_1^{(j)} x + C_0^{(j)}, x \in [0, 1)$  and

$$G(\alpha, \boldsymbol{\gamma}; \mathbf{x}) = -1 + \prod_{j=1}^{s} g(\alpha, \gamma_j; x_j), \quad \mathbf{x} = (x_1, \dots, x_s) \in [0, 1)^s.$$

Then for each vector  $\mathbf{m} \in \mathbf{Z}^s$  the Fourier coefficient  $\widehat{G}(\alpha, \gamma; \mathbf{m})$  of the function  $G(\alpha, \gamma; \cdot)$  satisfies the equality

(2) 
$$\widehat{G}(\alpha, \boldsymbol{\gamma}; \mathbf{m}) = \begin{cases} 0, & \text{if } \mathbf{m} = \mathbf{0}, \\ r(\alpha, \boldsymbol{\gamma}; \mathbf{m}), & \text{if } \mathbf{m} \neq \mathbf{0}. \end{cases}$$

**Theorem 2.** Let  $N \ge 1$  be an arbitrary integer and  $\xi_N = \{\mathbf{x}_0, \mathbf{x}_1, \dots, \mathbf{x}_{N-1}\}$  is an arbitrary net, composed of N points in  $[0, 1)^s$ . For each even integer  $\alpha \ge 2$  and an arbitrary vector of positive weights  $\boldsymbol{\gamma}$  the weighted diaphony  $F(\mathcal{T}; \alpha, \boldsymbol{\gamma}; \xi_N)$  of the net  $\xi_N$  satisfies the equality

$$F^{2}(\mathcal{T};\alpha,\gamma;\xi_{N}) = \frac{1}{\prod_{j=1}^{s} [1+2\gamma_{j}\zeta(\alpha)] - 1} \frac{1}{N^{2}} \sum_{n=0}^{N-1} \sum_{m=0}^{N-1} G(\alpha,\gamma;\mathbf{x}_{n} - \mathbf{x}_{m}),$$

where the function  $G(\cdot)$  is defined in the condition of Lemma 2.

3. Multivariate integration in the weighted Hilbert space  $H_{s,\alpha,\gamma}$ . Let  $\alpha > 1$ be an arbitrary real and  $\gamma = (\gamma_1, \gamma_2, \ldots, \gamma_s)$ , where  $\gamma_1 \ge \gamma_2 \ge \cdots \ge \gamma_s > 0$  is an arbitrary vector of weights. SLOAN and WOŻNIAKOWSKI [3] introduce the reproducing kernel weighted Hilbert space  $H_{s,\alpha,\gamma}$  with a norm  $\|\cdot\|_{s,\alpha,\gamma}$ . The space  $H_{s,\alpha,\gamma}$  is composed

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of 1-periodical with respect to all arguments complex-valued  $L_1([0,1)^s)$  functions f, defined on  $[0,1)^s$  with absolutely convergent Fourier series and for which  $||f||_{s,\alpha,\gamma} < \infty$ .

Let for an arbitrary integer  $N \ge 1$   $\xi_N = {\mathbf{x}_0, \mathbf{x}_1, \dots, \mathbf{x}_{N-1}}$  be a net composed of N points in  $[0, 1)^s$ . The worst-case error  $e(\mathcal{T}; s, \alpha, \gamma; \xi_N)$  of the integration in the space  $H_{s,\alpha,\gamma}$  is defined as

$$e(\mathcal{T}; s, \alpha, \boldsymbol{\gamma}; \xi_N) = \sup_{f \in H_{s,\alpha,\boldsymbol{\gamma}}, \|f\|_{s,\alpha,\boldsymbol{\gamma}} \le 1} \left\{ \left| \int_{[0,1)^s} f(\mathbf{x}) \, d\mathbf{x} - \frac{1}{N} \sum_{n=0}^{N-1} f(\mathbf{x}_n) \right| \right\}.$$

The next result is obtained.

**Theorem 3.** The worst-case error  $e(\mathcal{T}; s, \alpha, \gamma; \xi_N)$  of the integration in the reproducing kernel weighted Hilbert space  $H_{s,\alpha,\gamma}$ , which is based on using the net  $\xi_N$  and the weighted diaphony of the net  $\xi_N$  are connected with the equality

$$e(\mathcal{T}; s, \alpha, \boldsymbol{\gamma}; \xi_N) = \sqrt{\prod_{j=1}^{s} [1 + 2\gamma_j \zeta(\alpha)] - 1 \cdot F(\mathcal{T}; \alpha, \boldsymbol{\gamma}; \xi_N)}.$$

4. Proof of the main results. Proof of Theorem 1. The Weyl criterion (see KUIPERS and NIEDERREITER [4], Theorem 6.2) gives that the sequence  $\xi = (\mathbf{x}_n)_{n \ge 0}$  is uniformly distributed in  $[0, 1)^s$  if and only if the equality

(3) 
$$\lim_{N \to \infty} \frac{1}{N} \sum_{n=0}^{N-1} \exp(2\pi \mathbf{i} \langle \mathbf{m}, \mathbf{x}_n \rangle) = 0$$

holds for each vector  $\mathbf{m} \in \mathbf{Z}^s$  and  $\mathbf{m} \neq \mathbf{0}$ .

Let the sequence  $\xi$  be uniformly distributed in  $[0, 1)^s$ . From (3) for every  $\epsilon > 0$ there is an index  $N_{\epsilon}$  such that for each integer  $N \ge N_{\epsilon}$  the inequality

(4) 
$$\left|\frac{1}{N}\sum_{n=0}^{N-1}\exp(2\pi \mathbf{i}\langle \mathbf{m},\mathbf{x}_n\rangle)\right| < \epsilon$$

holds. From Definition 1 and (4) we have that for each even integer  $\alpha \geq 2$  and for an arbitrary vector  $\boldsymbol{\gamma}$  of positive weights

$$F_N^2(\mathcal{T}; \alpha, \boldsymbol{\gamma}; \xi) < \frac{\epsilon^2}{\prod_{j=1}^s [1 + 2\gamma_j \zeta(\alpha)] - 1} \sum_{\mathbf{m} \in \mathbf{Z}^s, \mathbf{m} \neq \mathbf{0}} r(\alpha, \boldsymbol{\gamma}; \mathbf{m}) = \epsilon^2.$$

The last inequality gives that the equality  $\lim_{N\to\infty} F_N(\mathcal{T}; \alpha, \gamma; \xi) = 0$  holds for each even integer  $\alpha \geq 2$  and an arbitrary vector  $\gamma$  of positive weights. We note that for each fixed vector  $\mathbf{m} \in \mathbf{Z}^s$  and  $\mathbf{m} \neq \mathbf{0}$  we have that

(5) 
$$\left|\frac{1}{N}\sum_{n=0}^{N-1}\exp(2\pi\mathbf{i}\langle\mathbf{m},\mathbf{x}_n\rangle)\right| \leq \sqrt{\frac{\prod_{j=1}^s [1+2\gamma_j\zeta(\alpha)]-1}{r(\alpha,\boldsymbol{\gamma};\mathbf{m})}}F_N(\mathcal{T};\alpha,\boldsymbol{\gamma};\boldsymbol{\xi}).$$

Let now the equality  $\lim_{N\to\infty} F_N(\mathcal{T};\alpha,\gamma;\xi) = 0$  holds for each even integer  $\alpha \geq 2$ and for an arbitrary vector  $\gamma$  of positive weights. Hence, the inequality (5) gives that

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the equality  $\lim_{N\to\infty} \frac{1}{N} \sum_{n=0}^{N-1} \exp(2\pi \mathbf{i} \langle \mathbf{m}, \mathbf{x}_n \rangle) = 0$  holds for each vector  $\mathbf{m} \in \mathbf{Z}^s$  and  $\mathbf{m} \neq \mathbf{0}$ . Then from (3) the sequence  $\xi$  is uniformly distributed in  $[0, 1)^s$ . Theorem 1 is completely proved.

**Proof of Theorem 2.** In Lemma 2 (ii) the Fourier coefficients of the function  $G(\cdot)$  are presented. So, we have the equality

(6) 
$$G(\alpha, \boldsymbol{\gamma}; \mathbf{x}) = \sum_{\mathbf{m} \in \mathbf{Z}^s} \widehat{G}(\alpha, \boldsymbol{\gamma}; \mathbf{m}) \exp(2\pi \mathbf{i} \langle \mathbf{m}, \mathbf{x} \rangle), \quad \forall \mathbf{x} \in [0, 1)^s.$$

Let  $\xi_N = {\mathbf{x}_0, \mathbf{x}_1, \dots, \mathbf{x}_{N-1}}$  be an arbitrary net composed of  $N \ge 1$  points in  $[0, 1)^s$ . From (2) and (6) we consecutively obtain

$$\begin{split} & \frac{1}{\prod_{j=1}^{s}[1+2\gamma_{j}\zeta(\alpha)]-1}\frac{1}{N^{2}}\sum_{n=0}^{N-1}\sum_{m=0}^{N-1}G(\alpha,\boldsymbol{\gamma};\mathbf{x}_{n}-\mathbf{x}_{m})\\ &=\frac{1}{\prod_{j=1}^{s}[1+2\gamma_{j}\zeta(\alpha)]-1}\frac{1}{N^{2}}\sum_{n=0}^{N-1}\sum_{m=0}^{N-1}\sum_{\mathbf{m}\in\mathbf{Z}^{s}}\widehat{G}(\alpha,\boldsymbol{\gamma};\mathbf{m})\exp(2\pi\mathbf{i}\langle\mathbf{m},\mathbf{x}_{n}-\mathbf{x}_{m}\rangle)\\ &=\frac{1}{\prod_{j=1}^{s}[1+2\gamma_{j}\zeta(\alpha)]-1}\sum_{\mathbf{m}\in\mathbf{Z}^{s},\mathbf{m\neq0}}r(\alpha,\boldsymbol{\gamma};\mathbf{m})\left|\frac{1}{N}\sum_{n=0}^{N-1}\exp(2\pi\mathbf{i}\langle\mathbf{m},\mathbf{x}_{n}\rangle)\right|^{2}\\ &=F_{N}^{2}(\mathcal{T};\alpha,\boldsymbol{\gamma};\xi_{N}). \end{split}$$

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